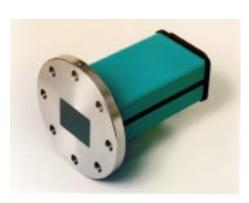
## **Microwave Distance Sensor**





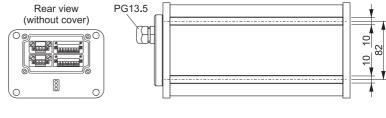
# **MWD-** | \*M-F21- \*\*-2KIR2

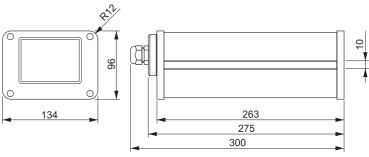


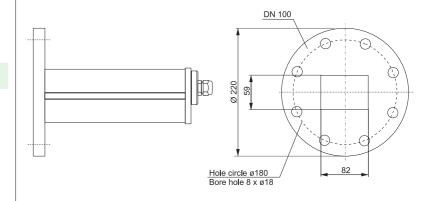
### **Characteristics**

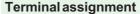
- · anti-collision monitoring
- · continuous level control measurement of solid and liquid media
- · measurement range to 60 m
- permissible in accordance with BAPT211TV3/2099
- · type of protection IP 67
- · serial interface RS 232 for measurement value transmission and sensor configuration
- 2 relay switching outputs, 1 analogue output (load-dependent current or voltage output)
- zone 11 explosion protection-anti-collision monitoring

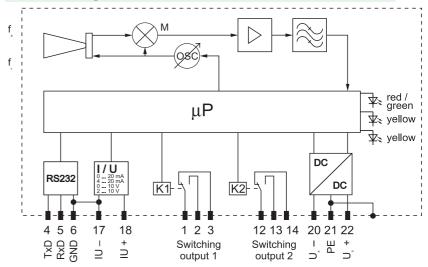












\*\*Housing variant

<sup>\*</sup>Measurement range

#### **Technical Data**

Microwave distance sensor

Measurement range

MWD | M .F21 - - 2KILIR2

MWD30M-F21-□-2KIUR2 2 ... 30 m MWD60M -F21 - - - 2KIUR2 4 ... 60 m

Housing variant / mounting

standard aluminium housing MWD \| \| M-F21-2KIUR2 version for level control MWD \| M-F21-DN100-2KIUR2

with mounting flange DN100, 1.4571 (V4A)

**Technical Data** 

Approvals / Certifications tested according to BAPT 211 TV 3/2099 (April 93)

BAPT type-examination certificate G132257J approved for Zone 11 according to DIN VDE 0165

Measurement

**Ex-Approval** 

2.00 ... 30.00 m (MWD30M-□) Measurement range 4.00 ... 60.00 m (MWD60M-\( \Brightarrow\)

Measurement frequency ≥ 12 Hz measurement method 'FAST' (MWD30M- )

measurement method 'FAST' (MWD60M- () ≥ 11 Hz

measurement method 'ACCURATE' ≥ 4 Hz

Error of measurement ≤ 2 % of end val. measurement method 'FAST'

≤0.35 % of end val. measurement method 'ACCURATE', Abstand > 4 m

metal 0.5 m x 0.5 m, 90°  $\pm$  0.1° (MWD30M- $\square$ ) Standard target metal 1.0 m x 1.0 m, 90° ± 0.1° (MWD60M-\( \Brace ) Temperature drift ≤ 2.5 % over the entire temperature range

Accept. angle of the scan beam approx. ± 5° horizontal, at -3 dB

approx. ± 8° vertical, at -3 dB

Transmission frequency 24.00 ... 24.25 GHz Transmission power  $\leq$  500 mW (EIRP)

**Power supply** 

DC 20 ... 30 V (PELV / SELV) Nominal voltage U<sub>B</sub>

Ripple ± 10 %ss, UB = 33 V

Bias current I, ≤ 600 mA

Relay switching outputs

permanent contact load  $2 A, 60 VAC, \cos \varphi = 0.7 (PELV / SELV)$ 

measurement method 'FAST' (MWD30M- $\square$ ) switching frequency > 6 Hz ≥ 5 Hz measurement method 'FAST' (MWD60M
)

 $\geq$  2 Hz measurement method 'ACCURATE'

0.00 ... 10.00 m, adjustable switching hysteresis

**Analogue output** to be operated load-dependent as current or voltage output

load  $R_i \le 500 \Omega$ current output

configurable: 0 / 4 ... 20 mA (4 ... 20 mA with 3.0 mA fault current)

load  $R_{_{I}} \ge 10 \text{ k}\Omega$ voltage output

configurable: 0 / 2 ... 10 V (2 ... 10 V with 1.5 V fault voltage)

RS 232 interface output of measured values, sensor configuration

9600 bit/s, 8 data bits, 1 stop bit, no parity

Display

LED "Run/Error" GREEN continuous: sensor ready for operation,

GREEN flashing:

signal quality ≥ 70 % sensor ready for operation,

signal quality < 70 % (excess gain) RED flashing: sensor not ready for operation,

interfering object at close range sensor defective, hardware error

RED continuous: LED "Relay 1", LED "Relay 2"

no object in the switching ranges YELLOW continuous: object in the switching ranges

approx. 2.8 kg (MWD \( \Bar{\text{MWD}} \) Weight **Environmental conditions** 

-25 °C ... +70 °C (248 K ... 343 K) operating temperature range storage temperature range -40 °C ... +85 °C (233 K ... 358 K)

Protection class, DIN 40 050 IP 67

shock test  $b \le 30 \text{ g}, T \le 11 \text{ ms}$ vibration test  $f \le 55 \text{ Hz}, a \le 0.35 \text{ mm}$ 

Standards conformity

coordination of insulation according to DIN EN 50 178 electrical isolation according to DIN EN 50 178

Electromagnetic compatibility according to DIN EN 50 081-1, DIN EN 50 081-2,

DIN EN 50 082-1, DIN EN 50 082-2

#### **Function**

The sensor functions on the principle of FMCW radar. The sensor continuously transmits triangular, frequency-modu-lated directional microwave radiation and receives the reflected radiation. Through the mixing of the transmitted and received signals, a signal delay occurs and, as distance is proportional to frequency, this delay is evaluated.

The microwave distance measurement with the the microwave distance sensors is not or is only slightly influenced by temperature, air pressure, air movement, mist, rain or snow.

#### Accessories

Three-way reflector MW-TRIP

Order No. 42480

Protective cover, MW-SH

Order No. 37267 **Mounting bracket** 

Order No. 38628

Parameterzation Software, MWD-Edit incl. RS232 interface cable 5

Order No. 46987

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