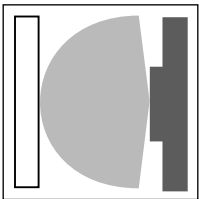


## Series -F20



### Optical scanner OSD3000-F20-M4



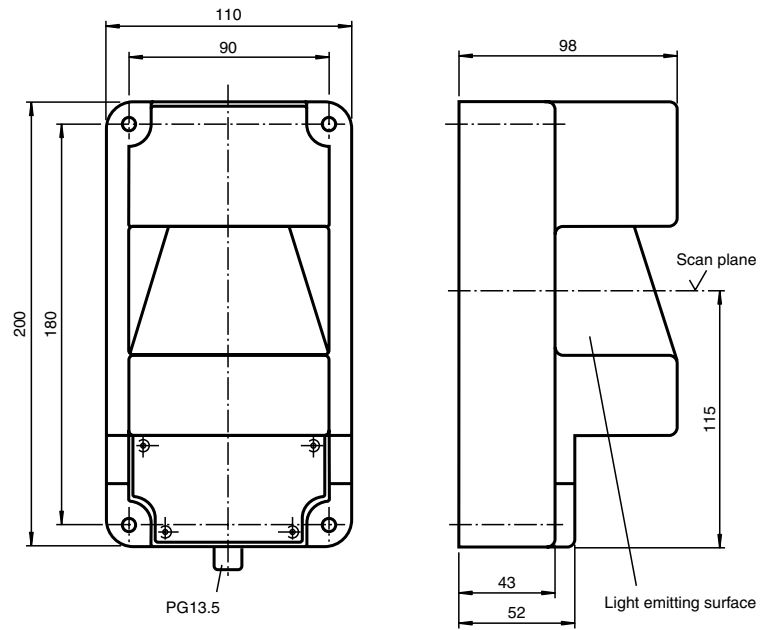
3000 mm



### Features

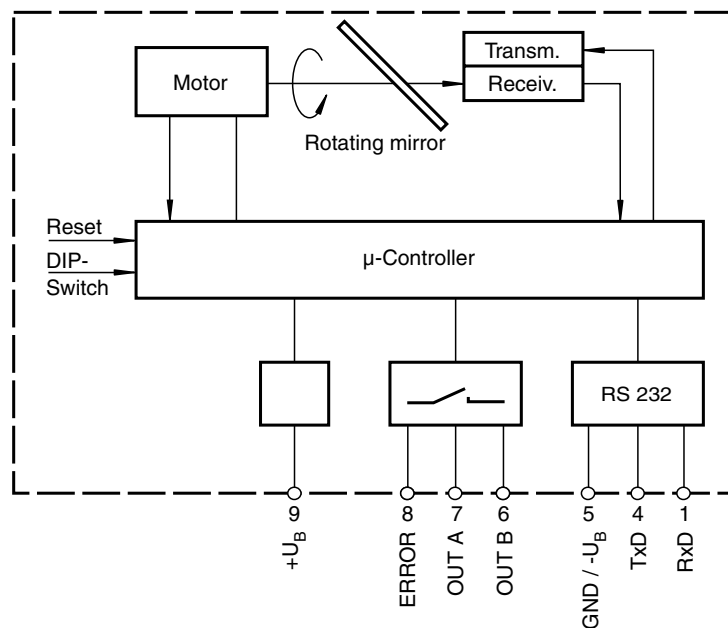
- Scanning zone 174°
- Choice of 2 free switching zones
- Supplied with control software
- TEACH-IN at the optimum threshold adjustment
- Self test
- Factory settings reset function
- Laser class 1, eyesafe
- Internal function monitoring

## Dimensions



Mounting accessories etc., see section "accessories"

## Electrical connection



**Valid for the whole family**

OSD3000-F20-M4

**General specifications**

Sensing range	0 ... 3000 mm
Reference target	Grey card 18 % (grey) ... 90 % (white) reflection, 200 mm x 200 mm
Light type	IR laser 780 nm . Laser class 1, eyesafe
Lifetime	Light source: ≥ 20000 h Motor: ≥ 40000 h
Ambient light limit	≤ 15000 Lux sun light ≤ 10000 Lux halogen light
Sampling frequency	10 Hz
temperature influence	Temperature compensation
Standard conformity	EN 60947-5-2

**Electrical specifications**

Rated operational voltage	$U_e$ 18 ... 30 V DC , ripple 10 % <sub>SS</sub>
---------------------------	--

**Indicating/operating means**

LED yellow	Object in zone A
LED green	Power on
LED red 1	Object in zone B
LED red 2	System fault
DIP-switch	Choice of 8 zone combinations programmed in an EEprom

**Output**

Output type	2 switch outputs pnp, NO/NC
Rated operational current	$I_e$ 200 mA , short circuit/overload protected
Voltage drop	$U_d$ ≤ 2.5 V
Switch-on delay	$t_{on}$ 100 ms
Range hysteresis	H adjustable
Repeat accuracy	≤ 2 %

**Ambient conditions**

Ambient temperature	0 ... 50 °C (273 ... 323 K)
Storage temperature	-40 ... 80 °C (233 ... 353 K)

**Mechanical specifications**

Protection degree	IP66 according to EN 60529
Connection type	Terminal compartment Pg13.5, core cross-section ≤ 2.5 mm <sup>2</sup>
Material	
Housing	ABS
Light exit	PMMA
Mass	1200 g

**Note**

**Measuring principle**

The laser beam of an optical distance measuring unit samples cyclicly through the scanning zone by means of a motor driven rotating mirror. When the measuring beam is reflected by objects within the sensing range, their distance and direction is determined. A series-connected microcontroller compares the positions of all detected objects with two freely configurable switching zones. If one or more objects lie within one switching zone, then the associated switch output responds.