









## **Model Number**

## AHS58-0\*

### **Features**

- **Industrial standard** housing Ø58 mm
- 16 Bit singleturn
- Data transfer up to 2 MBaud
- Optically isolated RS 422 interface
- **Zero-set function**
- Hollow shaft

## Description

This singleturn absolute encoder with modern fast technology transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface).

The resolution of the AHS58 is maximum 65536 steps per revolution.

The devices of the AHS58 series are equipped with a microcontroller.

The control module sends a clock bundle to the absolute encoder to obtain the position data. The rotary encoder then sends the position data synchronous to the cycles of the control module. It is possible to select the following items with function inputs

- the counting direction and
- the zero-set function (preset value)

The absolute encoder is mounted directly onto the application shaft, without any coupling. Rotation of the absolute encoder is prevented by a torque rest. The electrical connection is made by a 12-pin round plug connector. It is also possible to obtain a version with a 1 m cable connector.

## **Technical data**

### **Electrical specifications**

Operating voltage  $U_{\rm B}$ 10 ... 30 V DC No-load supply current I<sub>0</sub> max. 180 mA

± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit Linearity Output code

Gray code, binary code

Code course (counting direction) cw descending (clockwise rotation, code course descending)

#### Interface

SSI Interface type Monoflop time 20 ± 10 μs Resolution Single turn up to 16 Bit Overall resolution up to 16 Bit Transfer rate 0.1 ... 2 MBit/s U<sub>B</sub> - 2.5 V Voltage drop

Standard conformity **RS 422** Input 1

Selection of counting direction (V/R) Input type Signal voltage 10 ... 30 V High

0 ... 2 V Low Input current < 6 mA Signal duration > 10 ms Switch-on delay < 0.001 ms

#### Input 2

Input type zero-set (PRESET 1)

Signal voltage 10 ... 30 V High Low 0 ... 2 V Input current < 6 mA Signal duration ≥ 10 ms

#### Connection

Connector type 9416, 12-pin, type 9416L, 12-pin Ø7 mm, 6 x 2 x 0.14 mm<sup>2</sup>, 1 m Cable

#### Standard conformity

Vibration resistance

Switch-on delay

DIN FN 60529 IP64 Protection degree DIN EN 60068-2-3, no moisture condensation Climatic testing

< 100 ms

**Emitted interference** EN 61000-6-4:2007 Noise immunity EN 61000-6-2:2005 Shock resistance DIN EN 60068-2-27, 100 g, 3 ms

**Ambient conditions** -40 ... 85 °C (-40 ... 185 °F) Operating temperature -40 ... 85 °C (-40 ... 185 °F)

### Storage temperature **Mechanical specifications**

### Material

Combination 1 Housing: aluminium Flange: aluminium Shaft: stainless steel

DIN EN 60068-2-6, 10 g, 10 ... 2000 Hz

approx. 300 g (combination 1) Mass Rotational speed max. 3000 min

Moment of inertia 30 gcm<sup>2</sup> < 3 Ncm

Starting torque Shaft load

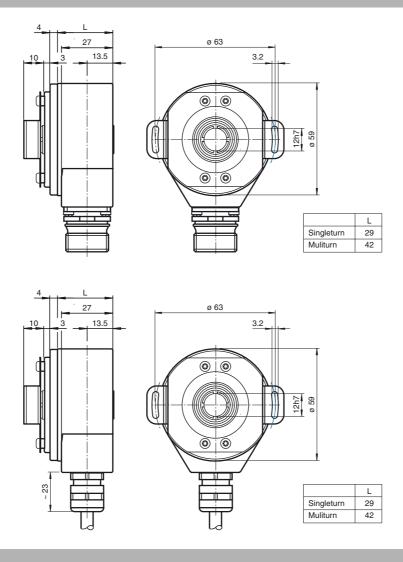
Angle offset ± 0.9 °

Axial offset static: ± 0.3 mm, dynamic: ± 0.1 mm Radial offset static: ± 0.5 mm, dynamic: ± 0.2 mm

## Approvals and certificates

**UL** approval cULus Listed, General Purpose, Class 2 Power Source

# **Dimensions**



## **Accessories**

9416

## **Electrical connection**

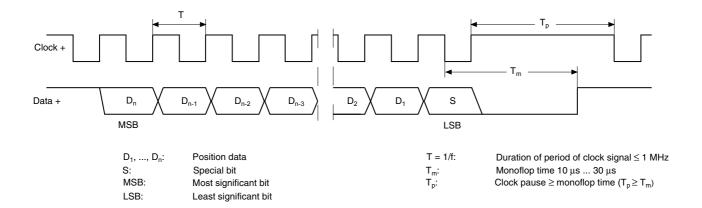
Signal	Cable Ø7 mm, 12-core	Connector 9416, 12-pin	Connector 9416L, 12-pin	Explanation
GND (encoder)	White	1	1	Power supply
U <sub>b</sub> (encoder)	Brown	2	8	Power supply
Clock (+)	Green	3	3	Positive cycle line
Clock (-)	Yellow	4	11	Negative cycle line
Data (+)	Grey	5	2	Positive transmission data
Data (-)	Pink	6	10	Negative transmission data
Reserved	Blue	7	12	Not wired, reserved
V/R	Red	8	5	Input for selection of counting direction
PRESET 1	Black	9	9	zero-setting input
Reserved	Violet	10	4	Not wired, reserved
Reserved	Grey/Pink	11	6	Not wired, reserved
Reserved	Red/Blue	12	7	Not wired, reserved
		9 8 10 7 12 6	9 1 12 2 10 3	

## **Description**

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

## SSI signal course Standard



## SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D<sub>n</sub>) and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T<sub>m</sub> has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T<sub>p</sub> has expired.
- After the clock sequence is complete, the monoflop time T<sub>m</sub> is triggered with the last falling pulse edge.
- The monoflop time T<sub>m</sub> determines the lowest transmission frequency.

## SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, 25 bits are transferred per data word in standard format.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first transmission, the 26<sup>th</sup> pulse controls data repetition. If the 26<sup>th</sup> pulse follows after an amount of time greater than the monoflop time T<sub>m</sub>, a new current data word will be transmitted with the following pulses.



If the pulse line is exchanged, the data word is generated offset. Ring slide operation is possible up to max. 13 bits.

## **Block diagram**

# Data + Receiver Data -Logic Clock + Clock generator

## Line length

Line length in m	Baudrate in kHz
< 50	< 400
< 100	< 300
< 200	< 200
< 400	< 100

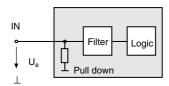
Rotary encoder

Interface electronics

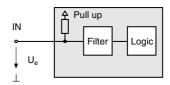
## Inputs

The selection of the counting direction input (V/R) is activated with 0-level. The zero-set input (PRESET 1) is activated with 1-level.

zero-set input (PRESET 1)



Input for selection of counting direction (V/R)



## **Accessories**

Accessories	Name/defining feature	Order code
Connectors	Cable socket	9416
Connectors	Cable socket	9416L

For additional information on the accessories, please see the "Accessories" section.

#### Order code 5 8 R Ν 0 Number of bits singleturn 12 4096 (standard) 13 8192 16 65536 Number of bits multiturn for singleturn-encoders 00 12 4096 (standard) 14 16384 **Output code** В Binary G Gray Option Н Hardware encoder Zero set function **Exit position** R Radial Connection type K1 Cable Ø7 mm, 6 x 2 x 0.14 mm<sup>2</sup>, 1 m AA Plug connector type 9416, 12-pin ΑB Plug connector type 9416L, 12-pin Shaft dimension/flange version Hollow shaft with Ø10 mm ОВА Hollow shaft with Ø12 mm Housing material Ν Aluminium Principle of operation s Singleturn Multiturn Wellenausführung н Hollow shaft **Data format**

A SSI (Synchronous Serial Interface)