

ASM58-0*

Features

- **Industrial standard** housing Ø58 mm
- 30 Bit multiturn
- Data transfer up to 2 MBaud
- Optically isolated RS 422 interface
- Recessed hollow shaft
- **Zero-set function**

Description

This multiturn absolute encoder with modern fast technology transmits a position value corresponding to the shaft setting via the SSI interface (Synchronous Serial Interface). The maximum resolution of the ASM58 is maximum 65536 steps per revolution at 16384 revolutions.

The devices of the ASM58 series are equipped with a microcontroller.

The control module sends a clock bundle to the absolute encoder to obtain position data. The rotary encoder then sends the position data synchronous to the cycles of the control module.

It is possible to select the following items with function inputs

- the counting direction and
- the zero-set function (preset value)

The absolute encoder is mounted directly onto the application shaft, without any coupling. Rotation of the absolute encoder is prevented by a torque rest The electrical connection is made by a 12-pin round plug connector. A version with a 1 m cable connector is also available.

Technical data

Interface

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MTTF _d	150 a
Mission Time (T _M)	20 a

1.9 E+11 at 6000 rpm and 20/40 N axial/radial shaft load L_{10h}

Diagnostic Coverage (DC) **Electrical specifications**

Functional safety related parameters

10 ... 30 V DC Operating voltage U_B No-load supply current I₀ max. 180 mA

± 2 LSB at 16 Bit, ± 1 LSB at 13 Bit, ± 0,5 LSB at 12 Bit Linearity

Output code Gray code, binary code

Code course (counting direction) cw descending (clockwise rotation, code course

descending)

Interface type SSI $20 \pm 10 \, \mu s$ Monoflop time

Resolution

Single turn up to 16 Bit Multiturn 14 Bit Overall resolution up to 30 Bit Transfer rate 0.1 ... 2 MBit/s

U_B - 2.5 V Voltage drop **RS 422** Standard conformity

Input 1 Input type Selection of counting direction (V/R)

Signal voltage High 10 ... 30 V 0 ... 2 V Low Input current < 6 mA

Signal duration ≥ 10 ms Switch-on delay < 0.001 ms

Input 2 zero-set (PRESET 1) Input type

Signal voltage 10 ... 30 V High Low 0 ... 2 V Input current < 6 mA

Signal duration > 10 ms Switch-on delay < 100 ms

Connection type 9416, 12-pin, type 9416L, 12-pin Connector Cable Ø7 mm, 6 x 2 x 0.14 mm², 1 m

Standard conformity

DIN EN 60529, IP65 Protection degree Climatic testing DIN EN 60068-2-3, no moisture condensation EN 61000-6-4:2007 **Emitted interference**

Noise immunity EN 61000-6-2:2005 Shock resistance DIN EN 60068-2-27, 100 g, 3 ms

Vibration resistance DIN EN 60068-2-6, 10 g, 10 ... 2000 Hz Ambient conditions

Operating temperature -40 ... 85 °C (-40 ... 185 °F) -40 ... 85 °C (-40 ... 185 °F) Storage temperature

Mechanical specifications Material

Combination 1 housing: powder coated aluminium

flange: aluminium shaft: stainless steel Combination 2 (Inox) housing: stainless steel

flange: stainless steel

shaft: stainless steel Mass approx. 460 g (combination 1)

approx. 800 g (combination 2) Rotational speed max. 12000 min -1

Moment of inertia 50 gcm² Starting torque < 5 Ncm

Shaft load Angle offset +09°

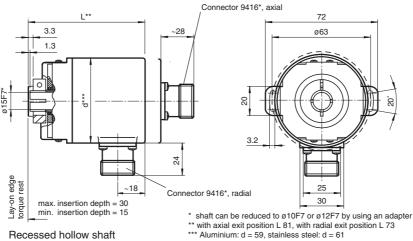
Axial offset static: ± 0.3 mm, dynamic: ± 0.1 mm Radial offset static: ± 0.5 mm, dynamic: ± 0.2 mm

Approvals and certificates

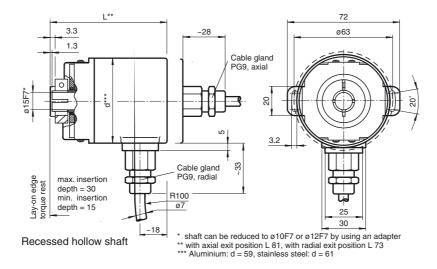
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UL approval cULus Listed, General Purpose, Class 2 Power Source

Dimensions



Recessed hollow shaft



Accessories

9416

Electrical connection

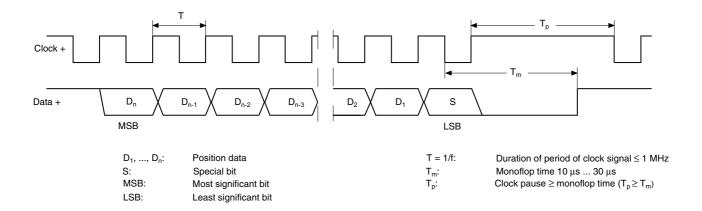
Signal	Cable Ø7 mm, 12-core	Connector 9416, 12-pin	Connector 9416L, 12-pin	Explanation
GND (encoder)	White	1	1	Power supply
U _b (encoder)	Brown	2	8	Power supply
Clock (+)	Green	3	3	Positive cycle line
Clock (-)	Yellow	4	11	Negative cycle line
Data (+)	Grey	5	2	Positive transmission data
Data (-)	Pink	6	10	Negative transmission data
Reserved	Blue	7	12	Not wired, reserved
V/R	Red	8	5	Input for selection of counting direction
PRESET 1	Black	9	9	zero-setting input
Reserved	Violet	10	4	Not wired, reserved
Reserved	Grey/Pink	11	6	Not wired, reserved
Reserved	Red/Blue	12	7	Not wired, reserved
		9 8 10 7 12 6	9 1 12 2 10 3	

Description

The Synchronous Serial Interface was specially developed for transferring the output data of an absolute encoder to a control device. The control module sends a clock bundle and the absolute encoder responds with the position value.

Thus only 4 lines are required for the clock and data, no matter what the resolution of the rotary encoder is. The RS 422 interface is optically isolated from the power supply.

SSI signal course Standard



SSI output format Standard

- At idle status signal lines "Data +" and "Clock +" are at high level (5 V).
- The first time the clock signal switches from high to low, the data transfer in which the current information (position data (D_n) and special bit (S)) is stored in the encoder is introduced.
- The highest order bit (MSB) is applied to the serial data output of the encoder with the first rising pulse edge.
- The next successive lower order bit is transferred with each following rising pulse edge.
- After the lowest order bit (LSB) has been transferred the data line switches to low until the monoflop time T_m has expired.
- No subsequent data transfer can be started until the data line switches to high again or the time for the clock pause T_p has expired.
- After the clock sequence is complete, the monoflop time T_m is triggered with the last falling pulse edge.
- ullet The monoflop time T_m determines the lowest transmission frequency.

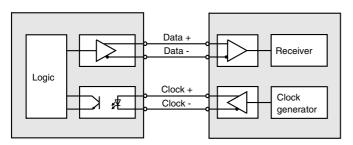
SSI output format ring slide operation (multiple transmission)

- In ring slide operation, multiple transmission of the same data word over the SSI interface makes it possible to offer the possibility of detecting transmission errors.
- In multiple transmission, 25 bits are transferred per data word in standard format.
- If the clock change is not interrupted after the last falling pulse edge, ring slide operation automatically becomes active. This means that the information that was stored at the time of the first clock change is generated again.
- After the first transmission, the 26th pulse controls data repetition. If the 26th pulse follows after an amount of time greater than the monoflop time T_m, a new current data word will be transmitted with the following pulses.



If the pulse line is exchanged, the data word is generated offset. Ring slide operation is possible up to max. 13 bits.

Block diagram



Line length

Line length in m	Baudrate in kHz
< 50	< 400
< 100	< 300
< 200	< 200
< 400	< 100

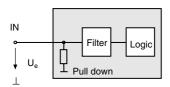
Rotary encoder

Interface electronics

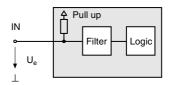
Inputs

The selection of the counting direction input (V/R) is activated with 0-level. The zero-set input (PRESET 1) is activated with 1-level.

zero-set input (PRESET 1)



Input for selection of counting direction (V/R)

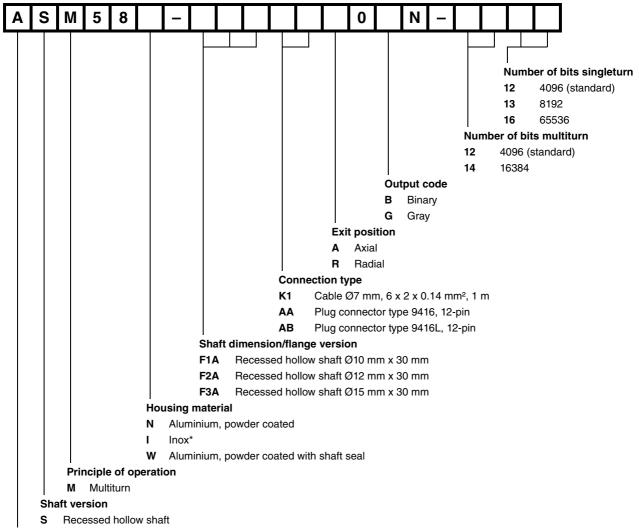


Accessories

Accessories	Name/defining feature	Order code	
Connectors	Cable socket	9416	
Connectors	Cable socket	9416L	

For additional information on the accessories, please see the "Accessories" section.

Order code



Data format

A SSI (Synchronous Serial Interface)

*Housing material I only available with axial exit position.