



Model Number

UVM36M-*****

Features

- Very small housing
- High climatic resistance
- 16 Bit multiturn
- **Analog output**
- Surge and reverse polarity protection

Description

This singleturn absolute encoder with internal magnetic sampling provides an analog output. The output voltage value is corresponding to the shaft

The encoder can be easily programmed by means of electrical inputs and pushbuttons.

Technical data

General specifications

Detection type magnetic sampling Measurement range min. 0 ... 22.5 max. 16 x 360 ° 16 Bit (12 bits/revolution) Resolution

Electrical specifications

Operating voltage U_B 12 ... 30 V DC , PELV

typ. 15 mA Current consumption Input 1

Input type lower limit of measurement range Signal voltage

12 ... 30 V DC High Signal duration ≥ 1 s

Input 2

Input type upper limit of measurement range Signal voltage

High

12 ... 30 V DC Signal duration ≥ 1 s

Analog output Output type 1 analog output, voltage Default setting rising slope at ccw rotation Linearity error ≤ 0.15 %

Connection

Connector M12 connector, 5 pin Cable Ø6 mm, 4 x 2 x 0.14 mm², 1 m

Standard conformity

Protection degree acc. DIN EN 60529 cable models: IP54 Connection side

connector models: IP65 Shaft side IP54

Climatic testing DIN EN 60068-2-3, no moisture condensation

Emitted interference EN 61000-6-4:2007 EN 61000-6-2:2005 Noise immunity

DIN EN 60068-2-27, 100 g, 6 ms Shock resistance Vibration resistance DIN EN 60068-2-6, 10 g, 10 ... 1000 Hz

Ambient conditions

cable, flexing: -5 ... 70 °C (-23 \vdots 158 °F), cable, fixed: -30 ... 70 °C (-22 ... 158 °F) Operating temperature connector models: -40 ... 85 °C (-40 ... 185 °F)

Storage temperature cable models: -30 ... 70 °C (-22 ... 158 °F) connector models: -30 ... 85 °C (-22 ... 185 °F)

< 3 Ncm

98 %, no moisture condensation Relative humidity

Mechanical specifications

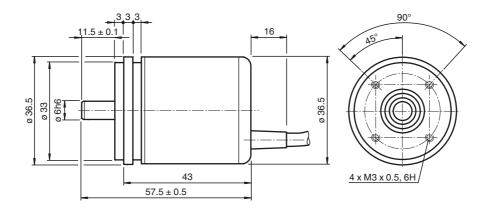
Material

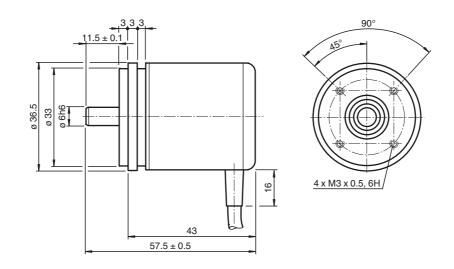
nickel-plated steel Housing Flange aluminum Shaft Stainless steel approx. 150 g, with cable Mass Rotational speed max. 12000 min ⁻¹ Moment of inertia 30 gcm²

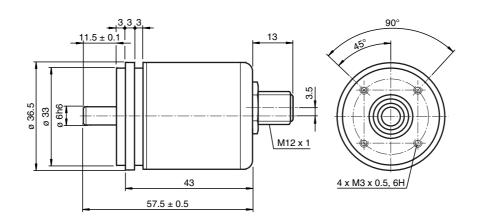
Starting torque Shaft load

Axial 40 N Radial 110 N

Dimensions







Electrical connection

Signal	Wire end	M12 connector		
Analog output	Green	1		
+V _s (encoder)	Red	2		
GND (encoder)	Yellow	3		
Set 2	White	4		
Set 1	Brown	5		
Shielding	Screen	Housing		
Pinout	-	2 (5) 4		

Description of rotary encoder functions

Default Settings

	Lower measuring range limit	Mid measuring range	Upper measuring range limit
Singleturn absolute rotary encoder	0	180°	360°
Multiturn absolute rotary encoder	0	8 x 360°	16 x 360°

Programming Encoders with No Operating Buttons

Scaling the measuring range

Use signal inputs "Set 1" and "Set 2" to scale the measuring range (minimum measuring range: 22.5°).

- 1. Turn the rotary encoder shaft to position 1 (lower measuring range limit).
- 2. Connect signal input "Set 1" to a high-potential source (12 VDC ≤ high potential ≤ +U_B) for 1 second.
- 3. Connect signal input "Set 1" to ground
- 4. Turn the rotary encoder shaft to position 2 (upper measuring range limit).
- 5. Connect signal input "Set 2" to a high-potential source (12 VDC ≤ high potential ≤ +U_B) for 1 second.
- 6. Connect signal input "Set 2" to ground

The analog output is now scaled to the programmed measuring range and the rotary encoder will operate in normal mode.

Resetting to the Default Setting

Connect the two signal inputs ("Set 1" and "Set 2") to a high-potential source (12 VDC ≤ high potential ≤ +U_B) for 1 second.

The measuring range is then reset to the default setting.

Programming Encoders with Operating Buttons

Scaling the measuring range

Use operating buttons "Lim1" and "Lim2" to scale the measuring range (minimum measuring range: 22.5°).

- 1. Press the two operating buttons ("Lim1" and "Lim2") simultaneously. Both LEDs will light up. Press and hold the operating buttons for 15 seconds until the two LEDs start to flash. The rotary encoder is now in programming mode.
- 2. Turn the rotary encoder shaft to position 1 (lower measuring range limit).
- 3. Press and hold operating button "Lim1" for 1 second. The green LED will now light up permanently.
- 4. Turn the rotary encoder shaft to position 2 (upper measuring range limit).
- 5. Press and hold operating button "Lim2" for 1 second.

The analog output is now scaled to the programmed measuring range and the rotary encoder will operate in normal mode. Only the green LED will light up.

Resetting to the Default Setting

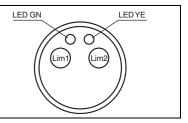
1. Press the two operating buttons ("Lim1" and "Lim2") simultaneously. Both LEDs will light up. Press and hold the operating buttons for 30 seconds. After 15 seconds, the two LEDs will start to flash.

When the green LED goes out and the yellow LED lights up permanently, the measuring range is reset to the default setting.

Status LEDs

The rotary encoder is equipped with two status LEDs. These LEDs have three possible states: off, flashing, or on. The LEDs use different combinations of these states to indicate the status of the rotary encoder.

Yellow LED	Green LED	Description
On	Off	Rotary encoder operation using default settings
Off	On	Rotary encoder operation using scaled measuring range (customer- specific setting)
On	On	Programming mode initiated (temporary state)
Flashes	Flashes	Rotary encoder in programming mode
On	Flashes	Position 2 set, waiting for position 1
Flashes	On	Position 1 set, waiting for position 2

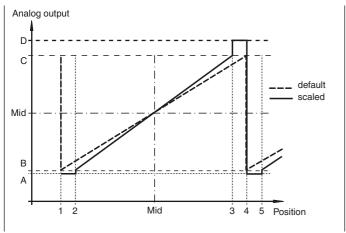


Analog Output Properties

Depending on its design, the rotary encoder projects the current angular position of the rotary encoder shaft in an analog current or voltage value. The following graphic shows the values the output accepts at the various angular positions:

t161990 eng.xml

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Legend:

Encoder type ¹⁾		Angular position					
		1	2	Mid	3	4	5
Singleturn	Factory default setting	0°	-	180°	-	360°	-
	Scaled	0°	Lower measuring range limit	-	Upper measuring range limit	360°	Lower measuring range limit
Multiturn	Factory default setting	0°	-	2 ⁴ x 180°	-	2 ⁴ x 360°	
	Scaled ²⁾	0°	Lower measuring range limit	-	Upper measuring range limit	2 ⁿ x 360°	Lower measuring range limit

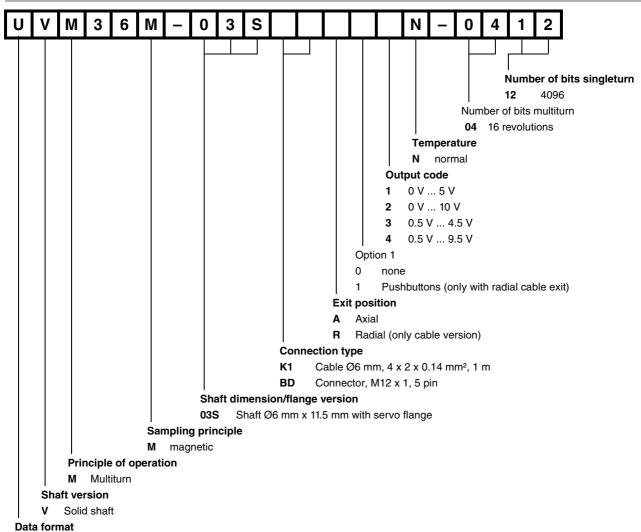
n = whole number from 1 to 16

1) See model number

2) Overflow at 360°, 720°, 1440°, 2880°, 5760°, etc. depending on the scale set.

Encoder output type			Analog output value	,	
	Α	В	Mid	С	D
0 V 5 V	-	0 V	2.5 V	5 V	-
0.5 V 4.5 V	0.25 V	0.5 V	2.5 V	4.5 V	4.75 V
0 V 10 V	-	0 V	5 V	10 V	-
0.5 V 9.5 V	0.25 V	0.5 V	5 V	9.5 V	9.75 V
4 mA 20 mA	3.6 mA	4 mA	12 mA	20 mA	22 mA
0 mA 20 mA	-	0 mA	10 mA	20 mA	-

Order code



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U Analog voltage output