







### **Model Number**

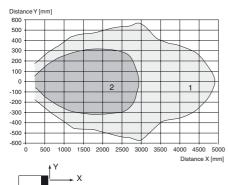
UC2500-F65-FE2R2-V15

### **Features**

- Level indication
- · Frequency output
- Programmable by means of Interface (see accessories) and SON-PROG
- Synchronization options
- Temperature compensation

### **Diagrams**

# Characteristic response curve



Curve 1: flat surface 100 mm x 100 mm Curve 2: round bar. Ø 25 mm

## **Technical data**

General specifications	
Sensing range	250 2500 mm
Adjustment range	250 2500 mm
Unusable area	0 250 mm
Standard target plate	100 mm x 100 mm
Transducer frequency	approx. 120 kHz

Nominal ratings

Time delay before availability t<sub>v</sub>

Limit data

Permissible cable length max. 300 m

Indicators/operating means

LED green Power on

LED yellow solid: switching state switch output flashing: misadjustment

Electrical specifications

Rated operational voltage U<sub>e</sub> 24 V DC

Operating voltage U<sub>B</sub> 12 ... 30 V (including ripple) In supply voltage interval 12 ... 20 V reduced sensitivity by

20% ... 0%

250 ms

Ripple  $\leq$  10 % No-load supply current I<sub>0</sub>  $\leq$  60 mA

Input

 $\begin{tabular}{ll} Input type & 1 Function input \\ Input voltage & \le Operating voltage \\ Level & low level: 0 ... 3 V \\ high level: <math>\ge$  15 V

Output

 $\begin{array}{ll} \text{Output type} & 1 \text{ Frequency output} \\ \text{Rated operational current I}_{\text{e}} & 300 \text{ mA} \\ \text{Default setting} & 250 \text{ mm} \dots 1500 \text{ mm} \end{array}$ 

Linearity ≤ 1.5 %

Output frequency 12.5 ... 125 Hz ( 125 ... 1250 Hz ) , adjustable

**Ambient conditions** 

**Mechanical specifications** 

Connection type Device connector M12 x 1 , 4-pin

Protection degree IP65

Material

Housing PBT

Transducer epoxy resin/hollow glass sphere mixture; polyurethane foam Installation position any position

Installation position any position
Mass 500 g

Compliance with standards and

directives

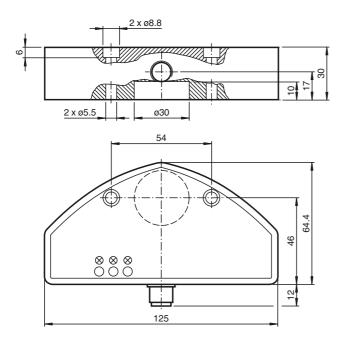
Standard conformity

Standards EN 60947-5-2:2007 IFC 60947-5-2:2007

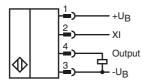
Approvals and certificates

UL approval cULus Listed, General Purpose
CSA approval cCSAus Listed, General Purpose

## **Dimensions**



## **Electrical Connection**



## **Pinout**

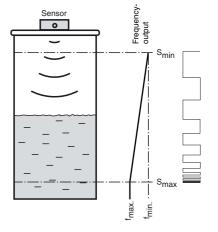


Wire colors in accordance with EN 60947-5-2

1 2 3 4	BN WH BU BK	(brown) (white) (blue) (black)
5	GY	(gray)

# **Additional Information**

## Function of the output



#### **Accessories**

#### V1-G-2M-PUR

Cable socket, M12, 4-pin, PUR cable

#### V1-G-2M-PVC

Cable socket, M12, 4-pin, PVC cable

#### V1-W-2M-PUR

Cable socket, M12, 4-pin, PUR cable

#### V1-W-2M-PVC

Cable socket, M12, 4-pin, PVC cable

#### 3RX4000-PF

PC interface

#### **Application ranges**

The design and function of this ultrasonic sensor make it ideal for filling level applications in small containers. The device has a frequency output. The frequency of the output signal is a measure of the current filling level.

### Assembly and connection

All components are contained in an encapsulated housing. The ultrasonic converter is in a slightly recessed position in the housing. The integrated circumferential seal allows the sensor to be used directly as a closure with integrated filling level measurement. The tank opening must have a diameter of 26 mm. It can be mounted on the tank using 2 M5 screws. The electrical connection is based on a 5-pin device connector, M12 x 1. The connections are protected against reverse polarity, short circuits and overloads. Shielded cables are recommended if there is electrical interference.

#### Setting

As delivered, the measuring range limits and the averaging are fixed (see Technical data). They can subsequently be adapted to the application via SONPROG using the interface (see Accessories).

#### **SONPROG**

The following parameters can be changed via SONPROG:

- Measuring range limits S<sub>min</sub> and S<sub>max</sub>
- · Frequency range
- · Blind zone
- · Averaging

Special programming options are available on request.

#### Operation

The filling level of a container is detected within the detection range. Filling levels between the measuring range limits  $(S_{min}, S_{max})$  are displayed in the form of a rectangular signal with variable frequency. The frequency output delivers the smallest frequency value at filling level  $S_{min}$  and the highest frequency at filling level  $S_{max}$ . The frequency characteristic between the two measuring range limits is linear.

Objects in the blind zone cause cause false signals. Install in such a way that the filling level cannot enter the blind zone.

#### **Function input XI**

The sensor is placed in standby mode by connecting a low level at the function input XI. The sensors then performs no measurements. The outputs retain the most recent status. As soon as function input XI is disconnected from the low level or a high level is connected, the sensor resumes its normal function.

The function input XI can be used during operation for the synchronisation of multiple sensors. This can be done by connecting external signals, e.g. from a controller (external synchronisation) or by simply connecting the function inputs of all sensors to be synchronised (internal synchronisation).