

600 900 1200 1500 1800 2100 2400 2700 3000 Distance X [mm]



0 300

Curve 1: flat surface 100 mm x 100 mm Curve 2: round bar, Ø 25 mm

Technical data
General specifications
Sensing range
Adjustment range
Unusable area
Standard target plate
Transducer frequency
Nominal ratings
Time delay before availability t <sub>v</sub>
Limit data
Permissible cable length
Indicators/operating means
LED green
LED yellow
Electrical specifications
Rated operational voltage Ue
Operating voltage UB
Ripple
No-load supply current I <sub>0</sub>
Input
Input type
Input voltage
Level
Output
Output
Output type
Rated operational current Ie
Default setting
Linearity
Output frequency
Ambient conditions
Ambient temperature
Storage temperature
Shock resistance
Vibration resistance
Mechanical specifications
Connection type
Protection degree
Material
Housing
Transducer
Installation position
Mass
Compliance with standards and directives
Standard conformity
Standards

Approvals and certificates

UL approval

CSA approval

# UC1500-F65-FE2R2-V15

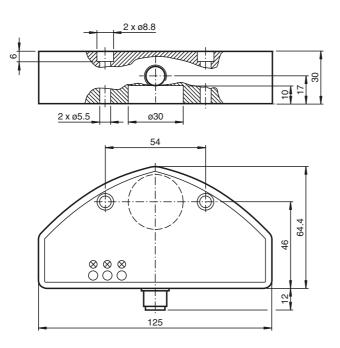
	200 1500 mm
	200 1500 mm
	0 200 mm
	20 mm x 20 mm
	approx. 200 kHz
t <sub>v</sub>	250 ms
	max. 300 m
	Power on
	solid: switching state switch output
	flashing: misadjustment
	24 V DC
	12 30 V (including ripple)
	In supply voltage interval 12 20 V reduced sensitivity by
	20% 0% < 10 %
	≤ 10 % ≤ 60 mA
	1 Function input
	≤ Operating voltage
	low level : 0 3 V
	high level : ≥ 15 V
	1 Frequency output
	300 mA
	200 mm 1500 mm
	≤ 1.5 %
	20 150 Hz ( 200 1500 Hz ) , adjustable
	-25 70 °C (-13 158 °F)
	-40 85 °C (-40 185 °F)
	30 g , 11 ms period
	10 55 Hz , Amplitude ± 1 mm
	Device connector M12 x 1 , 4-pin
	IP65
	PBT
	epoxy resin/hollow glass sphere mixture; polyurethane foam
	any position
	500 g
ind	
	EN 60947-5-2:2007
	EN 60947-5-2:2007 IEC 60947-5-2:2007
	cULus Listed, General Purpose
	cCSAus Listed, General Purpose

Subject to reasonable modifications due to technical advances.

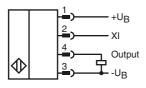
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# Dimensions



# **Electrical Connection**



Pinout

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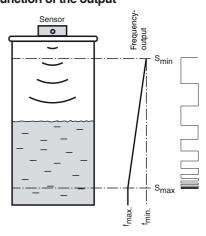
Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)
5	GY	(gray)

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**Additional Information** 



# Accessories

V1-G-2M-PUR Cable socket, M12, 4-pin, PUR cable

V1-G-2M-PVC

Cable socket, M12, 4-pin, PVC cable

V1-W-2M-PUR Cable socket, M12, 4-pin, PUR cable

### V1-W-2M-PVC

Cable socket, M12, 4-pin, PVC cable

3RX4000-PF PC interface

### Application ranges

The design and function of this ultrasonic sensor make it ideal for filling level applications in small containers. The device has a frequency output. The frequency of the output signal is a measure of the current filling level.

## Assembly and connection

All components are contained in an encapsulated housing. The ultrasonic converter is in a slightly recessed position in the housing. The integrated circumferential seal allows the sensor to be used directly as a closure with integrated filling level measurement. The tank opening must have a diameter of 26 mm. It can be mounted on the tank using 2 M5 screws. The electrical connection is based on a 5-pin device connector, M12 x 1. The connections are protected against reverse polarity, short circuits and overloads. Shielded cables are recommended if there is electrical interference.

#### Setting

As delivered, the measuring range limits and the averaging are fixed (see Technical data). They can subsequently be adapted to the application via SONPROG using the interface (see Accessories).

### SONPROG

The following parameters can be changed via SONPROG:

- Measuring range limits  ${\rm S}_{\rm min}$  and  ${\rm S}_{\rm max}$
- Frequency range
- Blind zone
- Averaging

Special programming options are available on request.

### Operation

The filling level of a container is detected within the detection range. Filling levels between the measuring range limits ( $S_{min}$ ,  $S_{max}$ ) are displayed in the form of a rectangular signal with variable frequency. The frequency output delivers the smallest frequency value at filling level  $S_{min}$  and the highest frequency at filling level  $S_{max}$ . The frequency characteristic between the two measuring range limits is linear.

Objects in the blind zone cause cause false signals. Install in such a way that the filling level cannot enter the blind zone.

#### Function input XI

The sensor is placed in standby mode by connecting a low level at the function input XI. The sensors then performs no measurements. The outputs retain the most recent status. As soon as function input XI is disconnected from the low level or a high level is connected, the sensor resumes its normal function.

The function input XI can be used during operation for the synchronisation of multiple sensors. This can be done by connecting external signals, e.g. from a controller (external synchronisation) or by simply connecting the function inputs of all sensors to be synchronised (internal synchronisation).

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