

CE

Model Number

PCV80-F200-SSI-V19

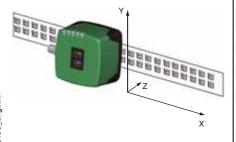
Read head for incident light positioning system

Features

- SSI interface
- Non-contact positioning on Data Matrix code tape
- Mechanically rugged: no wearing parts, long operating life, maintenance-free
- High resolution and precise positioning, especially for facilities with curves and switch points as well as inclines and declines.
- Travel ranges up to 10 km, in X and Y direction

Diagrams

Coordinates



Technical data

General specifications
Passage speed v

Measuring range max. 10000 m Light type Integrated LED lightning (red) Read distance 80 mm Depth of focus ± 15 mm Reading field 40 mm x 25 mm 100000 Lux Ambient light limit

± 0.1 mm

≤ 12.5 m/s

Resolution **Nominal ratings**

Camera

CMOS, Global shutter Type Processor

Clock pulse frequency 600 MHz

Speed of computation 4800 MIPS Functional safety related parameters MTTF_d 20 a

Mission Time (T_M) 10 a Diagnostic Coverage (DC) 0 %

Indicators/operating means

LED indicator 7 LEDs (communication, alignment aid, status information)

Electrical specifications 15 ... 30 V DC , PELV Operating voltage U_B No-load supply current I₀ max. 200 mA

Power consumption P₀ 3 W Interface 1

Interface type SSI interface

Data output code Gray code, binary code, programmable

 $T_m = 10 \mu s$ Monoflop time 100 ... 1000 kHz Clock frequency Query cycle time ≥ 3 ms

Pause time tp ≥ 20 µs double request possible, if $t_p \le 10 \ \mu s$

Interface 2 USB (serial comport) Interface type

Protocol 8E1 Transfer rate 38.4 ... 460.8 kBit/s

Input

Input type 1 to 2 functional inputs, programmable

Input impedance

Output

Output type 1 to 2 switch outputs, PNP, programmable, short-circuit

Switching voltage Operating voltage 150 mA each output Switching current

Standard conformity

Emitted interference FN 61000-6-4:2007 + A1:2011 Noise immunity EN 61000-6-2:2005 Shock resistance

EN 60068-2-27:2009 Vibration resistance EN 60068-2-6:2008

Ambient conditions

Operating temperature $0 \dots 60 \ ^{\circ}\text{C} \ (32 \dots 140 \ ^{\circ}\text{F}) \ , \ \ ^{-20} \dots 60 \ ^{\circ}\text{C} \ (^{-4} \dots 140 \ ^{\circ}\text{F})$

(noncondensing; prevent icing on the lens!) Relative humidity 90 %, noncondensing

Mechanical specifications

Connection type 8-pin. M12 x 1 connector

Protection degree IP67

Material

Housing PC/ABS approx. 160 g

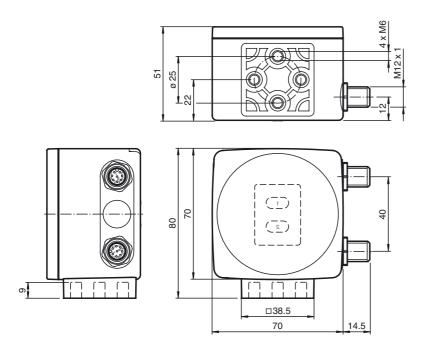
Approvals and certificates

UL approval cULus Listed, General Purpose, Class 2 Power Source,

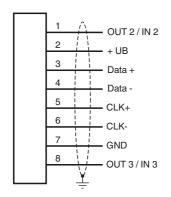
Type 1 enclosure

CCC approval Products with a maximum operating voltage of ≤36 V do not bear a CCC marking because they do not require

Dimensions



Electrical Connection



Pinout



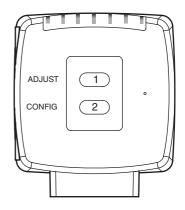
General

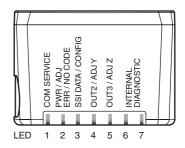
The PCV... reading head is part of the positioning system in the method for measurement by Pepperl+Fuchs. It consists of a camera module and an integrated illumination unit among other things. The reading head detects position marks, which are put on an adhesive code band in the form of Data Matrix code. The mounting of the code band is as a rule stationary on a firm part of the plant (elevator shaft, overhead conveyor mounting rails...); that of the reading head is parallel on the moving "vehicle" (elevator car, overhead conveyor chassis...).

Mounting and commissioning

Mount the reading head such that its optical surface captures the optimal read distance to the code band (see Tech-

Additional Information





Accessories

V19-G-ABG-PG9

Cable socket, M12, 8-pin, shielded, non pre-wired

V19-G-ABG-PG9-FE

Cable socket, M12, 8-pin, shielded, non pre-wired

PCV-KBL-V19-STR-USB

USB cable unit with power supply

PCV-SC12

Grounding clip for PCV system

PCV Parameterization Tool

Configuration software for PCV Data Matrix positioning system

nical Data). The stability of the mounting and the guidance of the vehicle must be provided such that the depth of field of the reading head is not closed during operation. All reading heads can be optimally customized by parameterization for specific requirements.

Displays and Controls

The PCV... reading head allows visual function check and fast diagnosis with 7 indicator LEDs. The reading head has 2 buttons on the reverse of the device to activate the alignment aid and parameterization mode.

LEDs

LED	Color	Label	Meaning
1	Yellow	COM	USB interface, communication active
2	Green/red	Code recognized/not recognized, Error	
3	Yellow	SSI DATA/CONFIG	Data flow on SSI interface / configuration
4	Yellow	OUT2/ADJ Y	Output 2, Alignment aid Y
5	Yellow	OUT3/ADJ Z	Output 3, Alignment aid Z
6,7	red/green/yellow	INTERNAL DIAGNOSTICS	Internal diagnostics

Data protocol

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25
Data	XP21	XP20	XP19	XP18	XP17	XP16	XP15	XP14	XP13	XP12	XP11	XP10	XP9	XP8	XP7	XP6	XP5	XP4	XP3	XP2	XP1	XP0	Out	Wrn	Err
	MSB																					LSB	S	tatus bit	ts

Position data is coded in XP0 ... XP21 (MSB first)

Meaning of the status bits

Out	Err	Wrn	Meaning
Х	X	1	reserved
Х	1	Х	Error, error code in XP0 XP21
1	Х	Х	No codes in read window (XP0 XP21 = 0)

Error codes

Error code	Meaning
1	reverse reading head orientation (180° contorted)
2	position error: unsecure position codes in reading window
>1000	internal error

External parameterization

For external parameterization you require the parameterization code as Data Matrix with the desired reading head parameters. Data Matrix code cards for step-by-step external parameterization are printed in the reading heads operating instructions.

Parameterization is only possible within 10 minutes of switching on the reading head. If a button is pressed after 10 minutes subsequent to switching on, there is visual signaling via the LEDs (LED1, yellow/LED2, red/LED3, yellow/LED4, yellow/LED5, yellow flash for 2 seconds)

- The switchover from normal operation to parameterization mode is via button 2 on the reverse of the reading head. Button 2 must be pressed for more than 2 seconds. LED3 now flashes.
- Note: Parameterization mode automatically ends after 1 minute of inactivity. The reading head returns to normal operation and works with unchanged settings.
- Place the parameterization code in the view of the camera module. After recognition of the parameterization code, the green LED2 lights up for 1s. In the event of an invalid parameterization code, the red LED2 lights up for 2 s.
- A short press on button 2 ends the parameterization mode and the changed parameters are not stored volatile in the reading head.

Alignment aid for the Y and Z coordinates

The activation of the alignment aid is only possible within 10 minutes of switching on the reading head. The switchover from normal operation to "alignment aid operating mode is via button 1 on the reverse of the reading head.

- Press the button 1 for longer than 2 s. LED2 flashes green for a recognized code band. LED2 flashes red for an unrecognized code band.
- Z coordinate: If the distance of the camera to the code band too small, the yellow LED5 lights up. If the distance of the camera to the code band too large, the yellow LED5 lights up. Within the target range, the yellow LED5 flashes at the same time as the green LED2.
- Y coordinate: If the optical axis of the camera is too deep in relation to the middle of the code band, the yellow LED4 lights up. If the optical axis is too high, the yellow LED4 extinguishes. Within the target range, the yellow LED4 flashes at the same time as the green LED2.
- · A short press on button 1 ends the alignment aid and the reading head changes to normal operation.