

Dr.

Scott Johnson

Date

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08-26-09

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General Specifications:						
1. Motor type: 3 phase, wye w	nding, permanent magnet rotor, totally	enclosed, non-ventilated.				
2. Motor poles:				8		
Operating Speed, max				3300 RPM		
4. Base speed (max speed at p	eak torque), Ref:			2800 RPM		
Operating voltage at base sp	eed:			440 VAC RN	<i>I</i> S	
Continuous stall torque, max	, at max winding temperature in a 40C a	ambient:		56 Nm (496		
Winding temperature, max, i	n a 40C ambient:			140 degrees	s C	
8. Continuous stall current, max	x: ached to front mounting flange for conti			44.40 Amps	0 to peak	
9. Heatsink size, aluminum, att	ached to front mounting flange for conti	nuous torque specifications	S:	305 x 305 x	25.4mm (12 x 12 x 1.0 inch)	
Peak stall torque, max:				88 Nm (779	lb-in)	
Peak stall current, max:				83.86 Amps	0 to peak	
12. Rated Speed (Speed at max				2000		
Continuous output rating, m	c continous power) nax at rated speed: rated speed:			7.50 kW (10	.05 hp)	
Continuous torque, max, at	nax at rated speed: rated speed: rated speed:			35.8 Nm (31	7 lb-in)	
Continuous current, Ref, at	rated speed: for direct connection to AC line):			28.0 Amps (to peak	
Operating voltage, Ref (Not	for direct connection to AC line):			480 VAC RI	MS	
17. Insulation class.				1000 (Class) [)	
Housing temperature, max:	e at 25C +/- 5C:			125C (257F)		
19. Ke, +/-10%, phase to phase	e at 25C +/- 5C:			172 V/kRPM	•	
20. Ni (Silie), Nei, al 200 +/- 00	<i>)</i> .			1.42 Nm/Am	p (12.59 lb-in/Amp) 0 to peak	
21. Winding resistance, +/- 10%	6, phase to phase at 25C +/- 5C:			0.155 ohms		
22. Winding inductance, Ref, p	hase to phase:			4.99 MH		
23. Dielectric rating of motor po	ower connections (U, v, vv), to ground for	i secona:		1000 VAC R	RMS 50/60 Hz	
Audible noise, Ref, at 1 me	ter distance:			XX dBA		
25. Rotor inertia, +/- 10%:				0.02449 kg-	m² (0.21675 lb-in-sec²)	
26. Rotor balancing quality grad	ue.			G-0.3		
27. Friction torque, Ref:				0.88 Nm (7.8	•	
28. Friction torque, Ref, with sh	aft seal option installed:			1.24 Nm (11	•	
29. Cogging torque, Ref:				0.62 Nm (5.4	46 lb-in) peak to peak	
30. Thermal resistance, Ref, wi				0.35 degree	s C/watt	
31. Thermal time constant, Ref	, winding to ambient:			97 minutes		
32. Product weight, Ref:				61.6 kg (135	·	
33. Shipping weight, Ref:				66.87 kg (14		
34. Operating ambient tempera	ture:			0C to 40C (3	32F to 104F)	
<u>notes:</u>						
	pecifications, provided for reference only					
Speed, torque and current sp	ecifications are for operation with Allen	-		•		
Doclarell	CONFIDENTIAL AND PROPRIETARY INFORMATION	Engineering Specificati	on Electrical		neet 2 of	5
Rockwell	THIS DOCUMENT CONTAINS CONFIDENTIAL AND PROPRIETARY INFORMATION OF ROCKWELL AUTOMATION, INC. AND MAY NOT BE USED, COPIED OR	MPM-B215	4F-SJ74AA	Size	40000070000	Ver
Automation	DISCLOSED TO OTHERS, EXCEPT WITH THE AUTHORIZED WRITTEN PERMISSION OF ROCKWELL AUTOMATION, INC.			A	10000073869	01
		Dr. Scott Johnson	Date 08-26-	-09		

General Specifications, continued:	20C to 70C / 22E to 159E\
35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	5% to 95%
57. Liquia 7 dust protection.	IF00
56. Shock, max, o msec duration.	20 g peak
39. Vibration, max, 30 to 2000 Hz:	2.5 g peak
+U. Shar material.	
41. Paint, color:41. Paint, color:	Black
42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications: 1. SIN, COS waveform output:	1024 sinusoids/rev
2 SIN COS waveform amplitude + 10%	1.0 VAC peak to peak
2. SIN, COS waveform amplitude, ± 10%: 3. SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC:	2.2 to 2.8 VDC
5. EPWR 5V continuous input current.max. at 5.0 VDC:	N/A
4. EPWR 5V (encoder power) input voltage: 5. EPWR 5V continuous input current,max, at 5.0 VDC: 6. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive: 7. EPWR 9V (encoder power) input voltage:	N/A
7. EPWR 9V (encoder power) input voltage: 8. EPWR 9V continuous input current,max, at 9.0 VDC:	7.0 to 12.0 VDC
3. EPWR 9V continuous input current,max, at 9.0 VDC:	80 mADC
9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	3.9 ADC
11. TS+, TS- thermostat continuous current, max, at 0.6 power factor:	1.6 Amps
10. TS+, TS- thermostat operating voltage, max: 11. TS+, TS- thermostat continuous current, max, at 0.6 power factor: 12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	DO 105 00001
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
	128 bytes
18. Memory storage capacity, EEPROM:	

Notes:

1. "Ref" denotes untoleranced specifications, provided for reference only.



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CONFIDENTIAL AND PROPRIETARY INFORMATION

Engineering Specification Electrical

Dr.

Size A

Sheet

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3

Ver **01**

Brake Specifications:

1.	Type: Spring-set holding	brake.	releases	when voltage applied.

	71 1 0 0 11	
2.	Holding torque, max:	70 Nm (619 lb-in)
3.	Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4.	Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	2.05 ADC
5.		11.76 Ohms
6.	Con reciciance, 17 1070, with motor operating at max continued claim torque rating in a 100 ambient.	16.46 Ohms
7.	Release time delay (when voltage applied), Ref:	200 msec
8.	Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	
	in external control circuit:	900 msec

9. Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device

120 msec

10. Rotational backlash, Ref, with brake engaged: 25 arc minutes

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Engineering Specification Electrical MPM-B2154F-SJ74AA

Dr. Scott Johnson Date 08-26-09

4 Sheet Size 10000073869

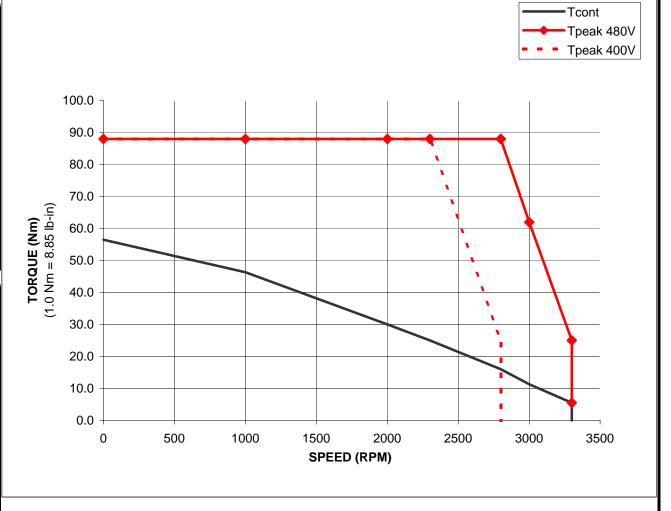
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MPM-B2154F-Sxx4xx Performance with 2094-BC07-M05, 3 Phase at 480 VAC Drive Input, 40C Motor Ambient

	TORQUE			
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V	
KEW	Nm	Nm	Nm	
0	56.5	88	88	
1000	46.3	88	88	
2000	30	88	88	
2300	25	88	88	
2800	16	88	25.1	
2800	16	88	0	
3000	11.3	62	#N/A	
3300	5.5	25	#N/A	
3300	0	5.5	#N/A	
#N/A	#N/A	#N/A	#N/A	
#N/A	#N/A	#N/A	#N/A	
#N/A	#N/A	#N/A	#N/A	

	TORQUE			
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V	
IXF IVI	lb-in	lb-in	lb-in	
0	500.1	778.9	778.9	
1000	409.8	778.9	778.9	
2000	265.5	778.9	778.9	
2300	221.3	778.9	778.9	
2800	141.6	778.9	222.2	
2800	141.6	778.9	0.0	
3000	100.0	548.7	#N/A	
3300	48.7	221.3	#N/A	
3300	0.0	48.7	#N/A	
#N/A	#N/A	#N/A	#N/A	
#N/A	#N/A	#N/A	#N/A	
#N/A	#N/A	#N/A	#N/A	



Notes:

1. Nm torque values shown are converted from tested lb-in data.

Rockwell Automation

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	Engineering Specification Electrical				
1	MPM-B2154F-SJ74AA				
	Dr.	Scott Johnson	Date	08-26-09	

Sh	eet	5	of	5
Size				Ver
Α		1000007	73869	01