

Rockwell
Automation

CONFIDENTIAL AND PROPRIETARY INFORMATION

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Engineering Specification Electrical	

MPM-B2154F-MJ74AA

Dr. Scott Johnson Date 08-26-09

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A 10000073869

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General Specifications:									
	nding, permanent magnet rotor, totally e	enclosed non-ventilated							
2. Motor poles:				8					
2 Operating Speed may				3300 R	РМ				
4 Base speed (max speed at pe	eak torque), Ref:			2800 R					
5. Operating voltage at base spe	eed:			440 VA	C DMC				
6 Continuous stall torque max	eed: , at max winding temperature in a 40C a	mbient		56 Nm	(496 lb-	in)			
7 Winding temperature max in	n a 40C ambient:			140 deg	arees C	,			
8 Continuous stall current max	··								
Heatsink size, aluminum, atta	:: ached to front mounting flange for contir	uous torque specifications	 S.	305 x 3				(1.0 inch)	
11. Peak stall current, max:				83.86 A		-			
12. Rated Speed (Speed at max	continous power)			2000	•	•			
	ax at rated speed:				V (10.05	hp)			
14. Continuous torque, max, at	rated speed:			35.8 Nn					
15. Continuous current, Ref, at i	rated speed:			28.0 An					
16. Operating voltage, Ref (Not	for direct connection to AC line):		••••••	480 VA	C RMS				
17. Insulation class:	······································		••••••	155C (C	Class F)	1			
18. Housing temperature, max:				 125C (2	257F)				
18. Housing temperature, max: 19. Ke, +/-10%, phase to phase at 25C +/- 5C:				172 V/kRPM 0 to peak					
20. Kt (sine), Ref, at 25C +/- 5C: 21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:				0.155 ohms					
22. Winding inductance, Ref, phase to phase:				4.99 mH					
23. Dielectric rating of motor power connections (U,V,W), to ground for 1 second:					1800 VAC RMS 50/60 Hz				
24. Audible noise, Ref, at 1 meter distance:					XX dBA				
25. Rotor inertia, +/- 10%: 0.02449 kg-m						(0.2167	75 lb-in-s	sec²)	
Rotor balancing quality grad	le:			G-6.3					
07 Full-tile te neve - Defe				\sim 00 NI \sim	n (7.8 lk	o-in)			
28. Friction torque, Ref, with sha	oft and antion installed:			4 24 Nm	n (11 lb	-in)			
29. Cogging torque, Ref:							eak to pe	eak	
30. Thermal resistance, Ref, wir				0.35 de	-	/watt			
31. Thermal time constant, Ref,	winding to ambient:			97 minu					
32. Product weight, Ref:				61.6 kg	•	•			
33. Shipping weight, Ref:				66.87 k		-			
Operating ambient temperat	ture:			0C to 4	0C (32F	to 104	F)		
Notes:									
	pecifications, provided for reference only								
Speed, torque and current speed	ecifications are for operation with Allen I								
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Rockwell	THIS DOCUMENT CONTAINS CONFIDENTIAL AND PROPRIETARY INFORMATION OF ROCKWELL AUTOMATION, INC. AND MAY NOT BE USED, COPIED OR	MPM-B2154	4F-MJ74AA	[]	Size	44		70000	Ver
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	·	Dr. Scott Johnson	Date 08-26	-09	<i>-</i> -				J .

35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	
20 Charle may 6 mans duration	20 a poak
39. Vibration, max, 30 to 2000 Hz:	
40. Shaft material:	
40. Shaft material: 41. Paint. color:	Black
42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	
1 SIN COS waveform output:	1024 sinusoids/rev
2. SIN, COS waveform amplitude, ± 10%:	1.0 VAC peak to peak
3. SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC:	2.5 VDC
4. EDWD 51/ (and a design actual) insultingly and	ΝΙ/Λ
5. EPWR 5V (encoder power) input voltage: 6. EPWR 5V continuous input current, max, at 5.0 VDC: 6. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	N/A
 EPWR 5V continuous input current,max, at 5.0 VDC: EPWR 5V inrush input current, max, when connected to Kinetix6000 drive: EPWR 9V (encoder power) input voltage: 	N/A
7. EPWR 9V (encoder power) input voltage:	7.0 to 12.0 VDC
8. EPWR 9V continuous input current,max, at 9.0 VDC:	80 mADC
7. EPWR 9V (encoder power) input voltage: 8. EPWR 9V continuous input current,max, at 9.0 VDC: 9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	3.9 ADC
	050.77.16
11. TS+, TS- thermostat continuous current, max, at 0.6 power factor:	1.6 Amps
12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	······································
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
18. Memory storage capacity, EEPROM:	128 bytes

Notes:

1. "Ref" denotes untoleranced specifications, provided for reference only.



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Brake Specifications:

1.	Type: Spring-set holding	brake, r	eleases v	when ν	oltage applied.

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2	2. Holding torque, max:	70 Nm (619 lb-in)
3	3. Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4	1. Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	2.05 ADC
5	5. Coil resistance, +/-10%, at 25C +/- 5C:	11.76 Ohms
6	6. Coil resistance, +/-10%, with motor operating at max continuous stall torque rating in a 40C ambient:	16.46 Ohms
7	7. Release time delay (when voltage applied), Ref:	200 msec
8	B. Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	•
	in external control circuit:	900 msec
Ś	D. Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device	•
	in external control circuit:	120 msec
1	Rotational backlash, Ref, with brake engaged:	25 arc minutes
1	Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:	1200 VAC RMS 50/60 Hz
		•

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Dr. Scott Johnson Date 08-26-09

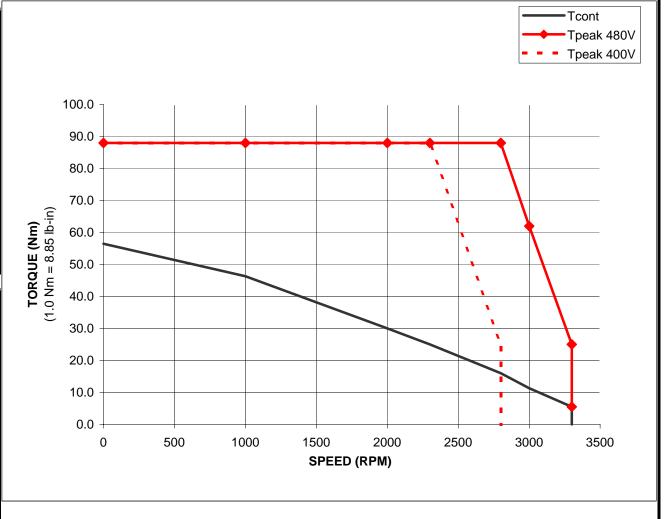
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MPM-B2154F-Mxx4xx Performance with 2094-BC07-M05, 3 Phase at 480 VAC Drive Input, 40C Motor Ambient

	TORQUE					
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V			
KEW	Nm	Nm	Nm			
0	56.5	88	88			
1000	46.3	88	88			
2000	30	88	88			
2300	25	88	88			
2800	16	88	25.1			
2800	16	88	0			
3000	11.3	62	#N/A			
3300	5.5	25	#N/A			
3300	0	5.5	#N/A			
#N/A	#N/A	#N/A	#N/A			
#N/A	#N/A	#N/A	#N/A			
#N/A	#N/A	#N/A	#N/A			

	TORQUE					
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V			
IXF IVI	lb-in	lb-in	lb-in			
0	500.1	778.9	778.9			
1000	409.8	778.9	778.9			
2000	265.5	778.9	778.9			
2300	221.3	778.9	778.9			
2800	141.6	778.9	222.2			
2800	141.6	778.9	0.0			
3000	100.0	548.7	#N/A			
3300	48.7	221.3	#N/A			
3300	0.0	48.7	#N/A			
#N/A	#N/A	#N/A	#N/A			
#N/A	#N/A	#N/A	#N/A			
#N/A	#N/A	#N/A	#N/A			



Notes:

1. Nm torque values shown are converted from tested lb-in data.



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