

Rockwell
Automation

CONFIDENTIAL AND PROPRIETARY INFORMATION

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Engineering Specification Electrical	

MPM-B2152F-MJ74AA

Dr. Scott Johnson Date 08-26-09

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Size				V

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Ver **01**

General Specifications:							
1. Motor type: 3 phase, wye wi	nding, permanent magnet rotor, totally	enclosed, non-ventilated.					
2. Motor poles:				8			
Operating Speed, max				4500 RPI	M		
4. Base speed (max speed at p	eak torque), Ref:			3150 RPI	M		
Operating voltage at base sp		440 VAC	RMS				
6. Continuous stall torque, max	, at max winding temperature in a 40C a	ambient:		33 Nm (2		n)	
Winding temperature, max, ir	n a 40C ambient:			140 degr	ees C		
8. Continuous stall current, max	c ached to front mounting flange for contin			43.54 Am			
Heatsink size, aluminum, atta	ached to front mounting flange for conting	nuous torque specifications	S:	305 x 305		4mm (12 x 12 x 1.0 inch)	
Peak stall torque, max:				72.3 Nm	(640 lb	o-in)	
Peak stall current, max:				98.06 Am	nps 0 to	o peak	
12. Rated Speed (Speed at max	continous power)			2500			
Continuous output rating, m	c continous power)			5.90 kW	(7.91 h	p)	
14. Continuous torque, max, at	rated speed:			22.8 Nm	(202 lb	o-in)	
15. Continuous current, Ref, at	rated speed: rated speed: rated speed:			26.4 Amp	os 0 to	peak	
Operating voltage, Ref (Not	rated speed:for direct connection to AC line):			480 VAC	RMS		
17. Insulation class.				155C (Cla	ass F)		
Housing temperature, max:	e at 25C +/- 5C:			125C (25	•		
19. Ke, +/-10%, phase to phase	e at 25C +/- 5C:			116 V/kRPM 0 to peak			
20. N. (SINE), Nei, al 200 +/- 00	/ .			0.30 Nill/Allip (0.43 ib-lil/Allip) 0 to peak			
21. Winding resistance, +/- 10%	6, phase to phase at 25C +/- 5C:			0.164 ohms			
22. Winding inductance, Ref, phase to phase:					5.27 MH		
23. Dielectric rating of motor po	wer connections (U,v,vv), to ground for	1 secona:		1000 VAC KIVIS 30/00 FIZ			
24. Audible noise, Ref, at 1 meter distance: XX dBA							
25. Rotor inertia, +/- 10%:	J			0.02059 1	kg-m² ((0.18224 lb-in-sec²)	
26. Rotor balancing quality grad	1e:			G-6.3			
27. Friction torque, Ref:				0.366 Nm	า (3.23	lb-in)	
28. Friction torque, Ref, with sh	aft seal option installed:			0.46 Nm	•	•	
29. Cogging torque, Ref:				0.256 Nm	•	lb-in) peak to peak	
Thermal resistance, Ref, wi	nding to ambient:			0.49 degi		/watt	
31. Thermal time constant, Ref.	, winding to ambient:			76 minute			
32. Product weight, Ref:				43.8 kg (9			
33. Shipping weight, Ref:				49.26 кд			
Operating ambient tempera	ture:			0C to 400	C (32F	to 104F)	
<u>notes:</u>							
	pecifications, provided for reference onl	-					
Speed, torque and current sp	ecifications are for operation with Allen			T			
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35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	5% to 95%
37. Liquid / dust protection:	IP66
38. Shock, max, 6 msec duration:	20 g peak
39. Vibration, max, 30 to 2000 Hz:	2.5 g peak
40. Shaft material:	
41. Paint, color:	Black
42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	
1. SIN, COS waveform output:	1024 sinusoids/rev
2. SIN, COS waveform amplitude, ± 10%: 3. SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC:	1.0 VAC peak to peak
4. EPWR 5V (encoder power) input voltage:	N/A
5. EPWR 5V continuous input current.max. at 5.0 VDC:	N/A
7. EPWR 9V (encoder power) input voltage:	7.0 to 12.0 VDC
8. EPWR 9V continuous input current,max, at 9.0 VDC:	80 mADC
9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	3.9 ADC
10. TS+, TS- thermostat operating voltage, max: 11. TS+, TS- thermostat continuous current, max, at 0.6 power factor: 12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	1.6 Amps
12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	RS 485, 9600 baud
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
	128 bytes
18. Memory storage capacity, EEPROM:	

Notes:

1. "Ref" denotes untoleranced specifications, provided for reference only.



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Brake Specifications:

1.	Type: S	pring-set	holding	brake.	releases	when	voltage	applied.

2. Holding torque, max:	70 Nm (619 lb-in)
3. Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4. Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	2.05 ADC
5. Coil resistance, +/-10%, at 25C +/- 5C:	11.76 Ohms
6. Coil resistance, +/-10%, with motor operating at max continuous stall torque rating in a 40C ambient:	16.46 Ohms
7. Release time delay (when voltage applied), Ref:	200 msec
8. Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	•
in external control circuit:	900 msec
9. Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device	•
in external control circuit:	120 msec
10. Rotational backlash, Ref, with brake engaged:	25 arc minutes
11. Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:	1200 VAC RMS 50/60 Hz
	•

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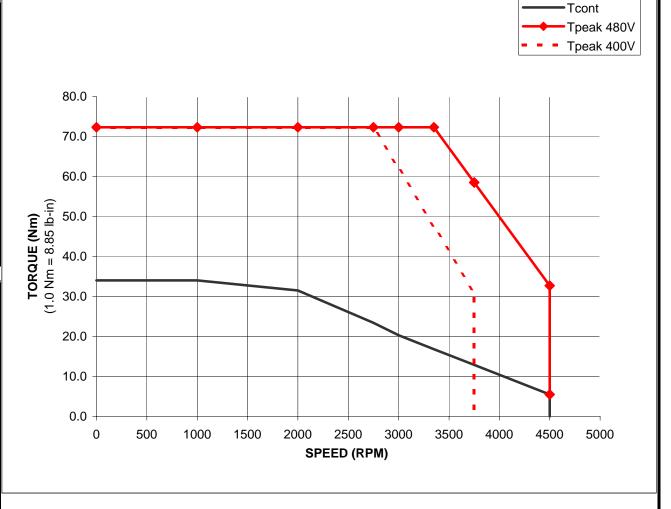
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MPM-B2152F-Mxx4xx Performance with 2094-BC07-M05, 3 Phase at 480 VAC Drive Input, 40C Motor Ambient

	TORQUE				
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V		
KEW	Nm	Nm	Nm		
0	34	72.3	72.3		
1000	34	72.3	72.3		
2000	31.5	72.3	72.3		
2750	23.4	72.3	72.3		
3000	20.3	72.3	62		
3350	16.8	72.3	47.5		
3750	12.9	58.5	30.98		
3750	12.9	58.5	0		
4500	5.5	32.7	#N/A		
4500	0	5.5	#N/A		
#N/A	#N/A	#N/A	#N/A		
#N/A	#N/A	#N/A	#N/A		

	TORQUE				
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V		
KLIM	lb-in	lb-in	lb-in		
0	300.9	639.9	639.9		
1000	300.9	639.9	639.9		
2000	278.8	639.9	639.9		
2750	207.1	639.9	639.9		
3000	179.7	639.9	548.7		
3350	148.7	639.9	420.4		
3750	114.2	517.8	274.2		
3750	114.2	517.8	0.0		
4500	48.7	289.4	#N/A		
4500	0.0	48.7	#N/A		
#N/A	#N/A	#N/A	#N/A		
#N/A	#N/A	#N/A	#N/A		



Notes:

1. Nm torque values shown are converted from tested lb-in data.

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