

Dr.

Scott Johnson

Date

08-26-09

General Specifications:								
1. Motor type: 3 phase, wye wi	nding, permanent magnet rotor, totally	enclosed, non-ventilated.						
2. Motor poles:				8				
Operating Speed, max					4500 RPM			
4. Base speed (max speed at p	eak torque), Ref:			3000 RPM				
Operating voltage at base sp	eed:			440 VAC RN	IS			
Operating voitage at base speed. Continuous stall torque, max, at max winding temperature in a 40C ambient:				5.99 Nm (53 lb-in)				
7. Winding temperature, max, ir	n a 40C ambient:			140 degrees C				
7. Winding temperature, max, in a 40C ambient: 8. Continuous stall current, max:			8.57 Amps 0 to peak					
			305 x 305 x 12.7mm (12 x 12 x 0.5 inch)					
10. Peak stall torque, max:				13.5 Nm (11	9 lb-in)			
11. Peak stall current, max:				22.12 Amps	0 to peak			
12. Rated Speed (Speed at max				4000				
13. Continuous output rating, m	ax at rated speed:			1.65 kW (2.2	1 hp)			
14. Continuous torque, max, at	rated speed:			3.9 Nm (35 lb	o-in)			
15. Continuous current, Ref, at	rated speed:			4.8 Amps 0 t	o peak			
16. Operating voltage, Ref (Not	rated speed: for direct connection to AC line):			480 VAC RM	IS			
17. Insulation class:				155C (Class	F)			
18. Housing temperature, max:				125C (257F)	125C (257F)			
19. Ke, +/-10%, phase to phase	e at 25C +/- 5C:			110 V/kRPM	0 to peak			
18. Housing temperature, max: 19. Ke, +/-10%, phase to phase at 25C +/- 5C: 20. Kt (sine), Ref, at 25C +/- 5C:			0.91 Nm/Amp (8.05 lb-in/Amp) 0 to peak					
21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:			2.6 ohms					
Winding inductance, Ref, pl	nase to phase:			23.46 MH				
23. Dielectric rating of motor po	wer connections (U, V, VV), to ground for	1 second:		1000 VAC K	MS 50/60 Hz			
24. Audible noise, Ref, at 1 met	ter distance:			XX dBA				
25. Rotor inertia, +/- 10%:	J			0.000983 kg	-m² (0.00870 lb-in-sec²)			
Rotor balancing quality grad	de:			G-6.3				
27. Friction torque, Ref:				0.114 Nm (1.	01 lb-in)			
28. Friction torque, Ref, with sh	aft seal option installed:			0.14 Nm (1.2	! lb-in)			
29. Cogging torque, Ref:				0.037 Nm (0.	33 lb-in) peak to peak			
30. Thermal resistance, Ref, wi	nding to ambient:			0.57 degrees	s C/watt			
31. Thermal time constant, Ref,	, winding to ambient:			26.5 minutes				
32. Product weight, Ref:				8.6 kg (19 lb)				
33. Shipping weight, Ref:					9 lb)			
Operating ambient tempera	ture:			0C to 40C (3	2F to 104F)			
Notes:								
 "Ref" denotes untoleranced s 	pecifications, provided for reference onl	y.						
Speed, torque and current sp	ecifications are for operation with Allen	•						
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General Specifications, continued: 35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	,
37. Liquid / dust protection:	IP66
38. Shock, max, 6 msec duration:	20
39. Vibration, max, 30 to 2000 Hz:	
40. Shaft material:	
41. Paint, color:	Black
42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	
1. SIN, COS waveform output:	1024 sinusoids/rev
2. SIN, COS waveform amplitude, ± 10%:	1.0 VAC peak to peak
SIN, COS waveform amplitude, ± 10%: SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC:	2.2 to 2.8 VDC
 EPWR 5V (encoder power) input voltage: EPWR 5V continuous input current,max, at 5.0 VDC: EPWR 5V inrush input current, max, when connected to Kinetix6000 drive: EPWR 9V (encoder power) input voltage: 	N/A
6. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	N/A
7. EPWR 9V (encoder power) input voltage:	7.0 to 12.0 VDC
8. EPWR 9V continuous input current.max. at 9.0 VDC:	80 mADC
9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	
10. TS+, TS- thermostat operating voltage, max:	250 Volts
11. TS+, TS- thermostat continuous current, max, at 0.6 power factor:	1.6 Amps
12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	RS 485, 9600 baud
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
40. Marray starage conscitu EEDDOM	128 bytes
18. Memory storage capacity, EEPROM:	

Notes:

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Engineering Specification Electrical
MDM D4202E C IZ4A

Dr.

MPM-B1302F-SJ74AA

08-26-09 Scott Johnson Date

Size Α

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Brake Specifications:

1	Type: Spring-set holding	hrake	releases	when	voltage applied

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2. Holding torque, max:	10.2 Nm (90 lb-in)
3. Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4. Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	0.64 ADC
5. Coil resistance, +/-10%, at 25C +/- 5C:	38 Ohms
6. Coil resistance, +/-10%, with motor operating at max continuous stall torque rating in a 40C ambient:	42 Ohms
7. Release time delay (when voltage applied), Ref:	110 msec
8. Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	•
in external control circuit:	160 msec
9. Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device	•
in external control circuit:	25 msec
10. Rotational backlash, Ref, with brake engaged:	48 arc minutes
11. Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:	1200 VAC RMS 50/60 Hz
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Engineering Specification Electrical

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Dr. Scott Johnson Date 08-26-09

Sheet 4 of Size 10000073869

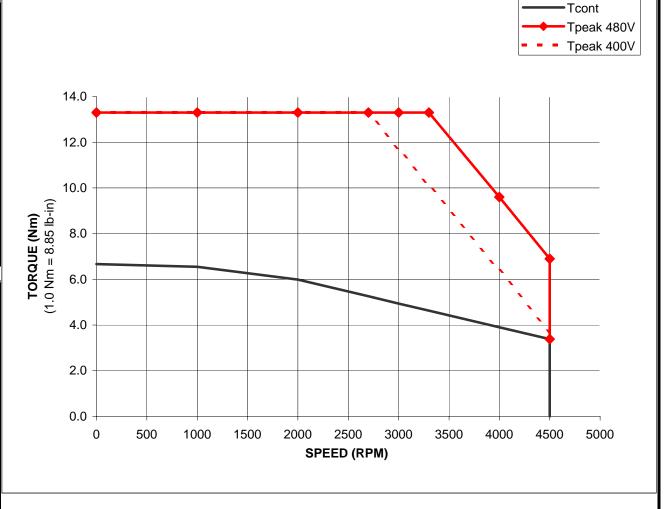
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MPM-B1302F-Sxx4xx Performance with 2094-BC01-M01, 3 Phase at 480 VAC Drive Input, 40C Motor Ambient

	TORQUE				
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V		
KEW	Nm	Nm	Nm		
0	6.67	13.3	13.3		
1000	6.55	13.3	13.3		
2000	5.99	13.3	13.3		
2700	5.26	13.3	13.3		
3000	4.94	13.3	11.7		
3300	4.63	13.3	10.1		
4000	3.9	9.6	6.4		
4500	3.38	6.9	3.7		
4500	0	3.38	#N/A		
#N/A	#N/A	#N/A	#N/A		
#N/A	#N/A	#N/A	#N/A		
#N/A	#N/A	#N/A	#N/A		

	TORQUE				
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V		
KEW	lb-in	lb-in	lb-in		
0	59.0	117.7	117.7		
1000	58.0	117.7	117.7		
2000	53.0	117.7	117.7		
2700	46.6	117.7	117.7		
3000	43.7	117.7	103.6		
3300	41.0	117.7	89.4		
4000	34.5	85.0	56.6		
4500	29.9	61.1	32.7		
4500	0.0	29.9	#N/A		
#N/A	#N/A	#N/A	#N/A		
#N/A	#N/A	#N/A	#N/A		
#N/A	#N/A	#N/A	#N/A		



Notes:

1. Nm torque values shown are converted from tested lb-in data.

Rockwell Automation

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	Engineering Specification Electrical					
1	MPM-B1302F-SJ74AA					
	Dr So	ott Johnson	Date	08-26-09		

Sh	eet	5	of	ţ	5
Size					Ver
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