

General Specifications:										
1. Motor type: 3 phase, wye wir	nding, permanent magnet rotor, totally e	enclosed,	non-ventilated.							
2. Motor poles:				8						
Operating Speed, max				5500 F	RPM					
				3400 RPM						
5. Operating voltage at base spe	eeu.					440 VAO KWO				
6. Continuous stall torque, max,	at max winding temperature in a 40C a	ambient:				6.55 N	6.55 Nm (58 lb-in)			
Winding temperature, max, in	n a 40C ambient:					_140 de	egrees	С		
8. Continuous stall current, max						9.20 A	9.20 Amps 0 to peak			
Continuous stall current, max: Heatsink size, aluminum, attached to front mounting flange for continuous torque specifications:			305 x 305 x 12.7mm (12 x 12 x 0.5 inch)							
						19.8 N	19.8 Nm (175 lb-in)			
Peak stall current, max:							Amps (0 to p	eak	
12. Rated Speed (Speed at max	continous power)					4000				
Continuous output rating, ma	ax at rated speed:					1.45 K	W (1.9			
14. Continuous torque, max, at	rated speed:					3.5 IVI	n (31 lk			
15. Continuous current, Ref, at a	rated speed: for direct connection to AC line):					4.5 An	nps 0 to	o pea	nk	
16. Operating voltage, Ref (Not	for direct connection to AC line):					480 V	AC RM	IS		
17. Insulation class:						155C (Class F)				
						1050 (0575)				
19. Ke, +/-10%, phase to phase	at 25C +/- 5C:					104 V/kRPM 0 to peak				
20. Kt (sine), Ref, at 25C +/- 5C:			0.86 Nm/Amp (7.61 lb-in/Amp) 0 to peak							
21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:			2.20 ohms							
Winding inductance, Ref, ph	nase to phase:					13 m⊦	1			
23. Dielectric rating of motor por	wer connections (U, v, vv), to ground for	i second	J:			1800 \	VAC RI	MS 5	0/60 Hz	
24. Audible noise, Ref, at 1 met	er distance:					XX dB	3A			
25. Rotor inertia, +/- 10%:	Jo.					0.0008	89 kg-n	n² (0.	00788 lb-in-sec²)	
26. Rotor balancing quality grad	le:					G-6.3				
27. Friction torque, Ref:				0.118 Nm (1.04 lb-in)						
28. Friction torque, Ref, with sha	aft seal option installed:					 0.38 Nm (3.4 lb-in)				
29. Cogging torque, Ref:						 0.045 Nm (0.40 lb-in) peak to peak				
Thermal resistance, Ref, wir	Cogging torque, Ref: Thermal resistance, Ref, winding to ambient:									
31. Thermal time constant, Ref,	31. Thermal time constant, Ref, winding to ambient:				28 minutes					
32. Product weight, Ref:	32. Product weight, Ref:			8.1 kg (17.8 lb)						
33. Shipping weight, Ref:	33. Shipping weight, Ref:			9.35 kg (20.6 lb)						
34. Operating ambient temperature:			0C to 40C (32F to 104F)							
Notes:						••				
1. "Ref" denotes untoleranced sp	pecifications, provided for reference onl	у.								
2. Speed, torque and current spe	ecifications are for operation with Allen	Bradley of	drives.							
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General Specifications, continued:	
35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	5% to 95%
37. Liquid / dust protection.	IP66
38. Shock, max, 6 msec duration:	20 g peak
39. Vibration, max, 30 to 2000 Hz:	2.5 g peak
40. Shaft material:	
41. Paint, color:	Black
42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	
1. SIN, COS waveform output:	1024 sinusoids/rev
2. SIN, COS waveform amplitude, ± 10%:	1.0 VAC peak to peak
3. SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC:	2.5 VDC
4. EPWR 5V (encoder power) input voltage:	
5. EPWR 5V continuous input current,max, at 5.0 VDC:	N/A
6. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	N/A
7. EPWR 9V (encoder power) input voltage:	7.0 to 12.0 VDC
8. EPWR 9V continuous input current,max, at 9.0 VDC:	80 m / D C
9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	3.9 ADC
10. TS+, TS- thermostat operating voltage, max:	2E0 \/alta
11. TS+, TS- thermostat continuous current, max, at 0.6 power factor:	1.6 Amps
12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
18. Memory storage capacity, EEPROM:	128 bytes
19. Encoder temperature data: Binary value of encoder temperature in degrees C.	
13. Enloader temperature data. Binary value of enloader temperature in degrees 6.	

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Engineering Specification Electrical

Dr.

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Brake Specifications:

1	Type: Spring-set holding	hraka	ralassas	whon	voltage	annlied
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	. Type: Opining Set Helding State, Foldage When Voltage applied.	
2	. Holding torque, max:	4.18 Nm (37 lb-in)
3	3. Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4	. Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	0.50 ADC
5	5. Coil resistance, +/-10%, at 25C +/- 5C:	48 Ohms
6	6. Coil resistance, +/-10%, with motor operating at max continuous stall torque rating in a 40C ambient:	53 Ohms
7	'. Release time delay (when voltage applied), Ref:	50 msec
8	B. Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	
	in external control circuit:	110 msec
ç). Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device	
	in external control circuit:	20 msec
1	Rotational backlash, Ref, with brake engaged:	45 arc minutes
1	Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:	1200 VAC RMS 50/60 Hz

Notes:

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Engineering Specification Electrical **MPM-B1153F-MJ74AA**

Dr. Scott Johnson Date 08-26-09

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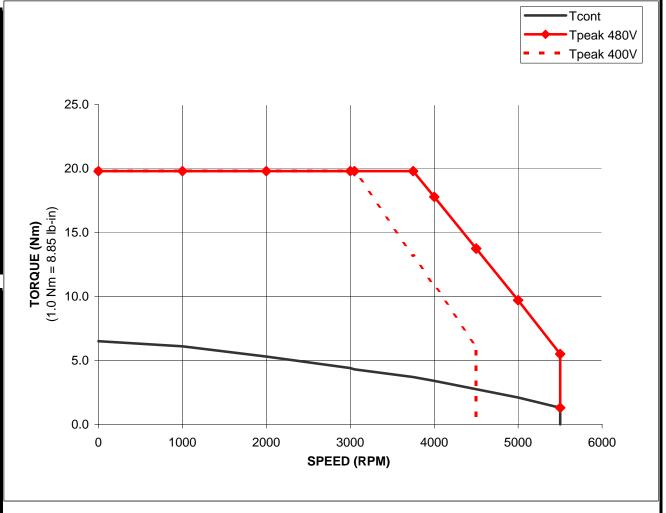
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MPM-B1153F-Mxx4xx Performance with 2094-BC02-M02, 3 Phase at 480 VAC Drive Input, 40C Motor Ambient

		TORQUE	
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V
KEW	Nm	Nm	Nm
0	6.5	19.8	19.8
1000	6.1	19.8	19.8
2000	5.3	19.8	19.8
3000	4.4	19.8	19.8
3050	4.3	19.8	19.8
3750	3.7	19.8	13.2
4000	3.4	17.78	10.84
4500	2.75	13.74	6.12
4500	2.75	13.74	0
5000	2.1	9.7	#N/A
5500	1.3	5.5	#N/A
5500	0	1.3	#N/A

	TORQUE				
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V		
KLIM	lb-in	lb-in	lb-in		
0	57.5	175.2	175.2		
1000	54.0	175.2	175.2		
2000	46.9	175.2	175.2		
3000	38.9	175.2	175.2		
3050	38.1	175.2	175.2		
3750	32.7	175.2	116.8		
4000	30.1	157.4	95.9		
4500	24.3	121.6	54.2		
4500	24.3	121.6	0.0		
5000	18.6	85.9	#N/A		
5500	11.5	48.7	#N/A		
5500	0.0	11.5	#N/A		



Notes:

1. Nm torque values shown are converted from tested lb-in data.

Rockwell Automation

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