

General Specifications:							
1. Motor type: 3 phase, wye wi	nding, permanent magnet rotor, totally	enclosed, non-ventilated.					
2. Motor poles:			8				
Operating Speed, max				5200 RPM			
4. Base speed (max speed at p	4. Base speed (max speed at peak torque), Ref:			3000 RPM			
Operating voltage at base sp	eed:			440 VAC RMS			
6. Continuous stall torque, max	, at max winding temperature in a 40C a	ambient:		4.74 Nm (42			
Winding temperature, max, in	n a 40C ambient:			140 degrees	C		
8. Continuous stall current, max	x: ached to front mounting flange for conti			6.17 Amps 0	to peak		
9. Heatsink size, aluminum, atta	ached to front mounting flange for conti	nuous torque specifications	S:	305 x 305 x 12.7mm (12 x 12 x 0.5 inch)			
10. Peak stall torque, max:				13.5 Nm (11	13.5 Nm (119 lb-in)		
11. Peak stall current, max:				21.19 Amps	0 to peak		
12. Rated Speed (Speed at max							
Continuous output rating, m	nax at rated speed:			1.40 kW (1.8	8 hp)		
14. Continuous torque, max, at	c continous power) nax at rated speed: rated speed:			3.32 Nm (29	lb-in)		
15. Continuous current, Ref, at	rated speed: for direct connection to AC line):			4.1 Amps 0 t	o peak		
Operating voltage, Ref (Not	for direct connection to AC line):			480 VAC RM	1S		
17. Insulation class:				1550 (Class	"155C (Class F)		
Housing temperature, max:				^{***} 125C (257F)			
19. Ke, +/-10%, phase to phase	e at 25C +/- 5C:			109 V/kRPM 0 to peak			
20. Ni (Silie), Nei, al 200 +/- 00	18. Housing temperature, max: 19. Ke, +/-10%, phase to phase at 25C +/- 5C: 20. Kt (sine), Ref, at 25C +/- 5C:			0.30 Nill/Allip (7.30 ib-ill/Allip) 0 to peak			
21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:			3.84 ohms				
22. Winding inductance, Ref, pl	hase to phase:			21.6 MH			
23. Dielectric rating of motor po	ower connections (U, V, VV), to ground for	1 second:		1000 VAC K	MS 50/60 Hz		
24. Audible noise, Ref, at 1 me	ter distance:			XX dBA			
25. Rotor inertia, +/- 10%:	J			0.00077 kg-r	m² (0.00681 lb-in-sec²)		
26. Rotor balancing quality grad	de:			G-6.3			
27. Friction torque, Ref:				0.09 Nm (0.8	30 lb-in)		
28. Friction torque, Ref, with sh	aft seal option installed:			0.38 Nm (3.4 lb-in)			
29. Cogging torque, Ref:				0.042 Nm (0.37 lb-in) peak to peak			
30. Thermal resistance, Ref, wi	nding to ambient:			0.54 degrees C/watt			
31. Thermal time constant, Ref	, winding to ambient:			24.5 minutes			
32. Product weight, Ref:				6.9 kg (15.2 lb)			
33. Shipping weight, Ref:							
Operating ambient tempera	34. Operating ambient temperature:			0C to 40C (32F to 104F)			
Notes:							
 "Ref" denotes untoleranced s 	pecifications, provided for reference only	y.					
Speed, torque and current sp	ecifications are for operation with Allen	•					
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	. Introduction reconstitution, inc.	Dr. Scott Johnson	Date 08-26-	09		0 1	

35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	
37. Liquid / dust protection:	IP66
38. Shock, max, 6 msec duration:	20 g peak
39. Vibration, max, 30 to 2000 Hz:	2.5 g peak
40. Shaft material:	
41. Paint, color:	Black
42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	
1. SIN, COS waveform output:	1024 sinusoids/rev
2. SIN, COS waveform amplitude, ± 10%:	1.0 VAC peak to peak
2 CIN COS voltago effect with respect to FCOM to 2 V/DC.	2 2 to 2 8 V/DC
4. EPWR 5V (encoder power) input voltage: 5. EPWR 5V continuous input current,max, at 5.0 VDC:	N/A
5. EPWR 5V (encoder power) input voltage: 6. EPWR 5V continuous input current, max, at 5.0 VDC: 6. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	N/A
0 EDVD 5V: 1: 4 4 4 5 6 0000 1:	N1/A
EPWR 5V inrush input current, max, when connected to Kinetix6000 drive: EPWR 9V (encoder power) input voltage: EPWR 9V continuous input current,max, at 9.0 VDC:	7.0 to 12.0 VDC
8. EPWR 9V continuous input current,max, at 9.0 VDC:	80 mADC
7. EPWR 9V (encoder power) input voltage: 8. EPWR 9V continuous input current,max, at 9.0 VDC: 9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	3.9 ADC
 10. TS+, TS- thermostat operating voltage, max: 11. TS+, TS- thermostat continuous current, max, at 0.6 power factor: 12. TS+, TS- thermostat continuous current, max, at 1.0 power factor: 	1.6 Amps
12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
18. Memory storage capacity, EEPROM:	128 bytes
19. Encoder temperature data: Binary value of encoder temperature in degrees C.	

Notes:

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Engineering Specification Electrical

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Ver **01**

Brake Specifications:

1.	Type: Spring-set holding	brake	releases	when voltage applied.

2.	Holding torque, max:	4.18 Nm (37 lb-in)
3.	Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4.		0.50 ADC
5.	Coil resistance, +/-10%, at 25C +/- 5C:	48 Ohms
6.	Con recolciance, if refe, man motor operating at max continued of the torque rating in a recomment.	53 Ohms
7.	Release time delay (when voltage applied), Ref:	50 msec
8.	Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	
	in external control circuit:	110 msec

Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device

in external control circuit:

10. Rotational backlash, Ref, with brake engaged:

11. Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:

1200 VAC RMS 50/60 Hz

Notes:

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Engineering Specification Electrical MPM-B1152F-SJ74AA

Dr. Scott Johnson 08-26-09

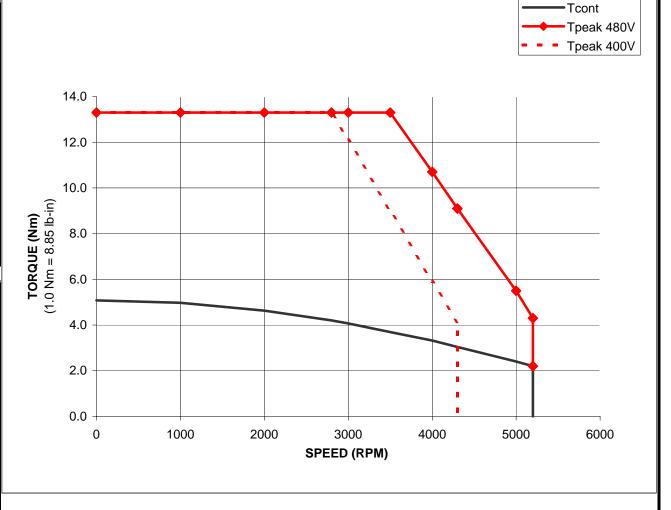
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Ver 01

MPM-B1152F-Sxx4xx Performance with 2094-BC01-M01, 3 Phase at 480 VAC Drive Input, 40C Motor Ambient

		TORQUE	
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V
KEW	Nm	Nm	Nm
0	5.08	13.3	13.3
1000	4.97	13.3	13.3
2000	4.63	13.3	13.3
2800	4.2	13.3	13.3
3000	4.07	13.3	12.1
3500	3.69	13.3	9
4000	3.32	10.7	5.9
4300	3.04	9.1	4.13
4300	3.04	9.1	0
5000	2.4	5.5	#N/A
5200	2.2	4.3	#N/A
5200	0	2.2	#N/A

		TORQUE	
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V
IXF IVI	lb-in	lb-in	lb-in
0	45.0	117.7	117.7
1000	44.0	117.7	117.7
2000	41.0	117.7	117.7
2800	37.2	117.7	117.7
3000	36.0	117.7	107.1
3500	32.7	117.7	79.7
4000	29.4	94.7	52.2
4300	26.9	80.5	36.6
4300	26.9	80.5	0.0
5000	21.2	48.7	#N/A
5200	19.5	38.1	#N/A
5200	0.0	19.5	#N/A



Notes:

1. Nm torque values shown are converted from tested lb-in data.

Rockwell Automation

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