

Rockwell
<b>Automation</b>

CONFIDENTIAL AND PROPRIETARY INFORMATION

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Engineering Specification Electrical
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MPM-A2153F-SJ74AA

Dr. Scott Johnson Date 08-26-09

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General Specifications:								
	nding, permanent magnet rotor, totally e	enclosed non-ventilated						
2. Motor poles:				8				
3 Operating Speed may				 3600 RPI	М			
4 Base speed (max speed at pe	eak torque), Ref:			3000 RPI				
5. Operating voltage at base spe	eed:			220 VAC				
6 Continuous stall torque max	eed: , at max winding temperature in a 40C a	mbient		34 Nm (3		n)		
7 Winding temperature max in	n a 40C ambient:			140 degr		-/		
8 Continuous stall current max	··					peak		
Heatsink size, aluminum, atta	:: ached to front mounting flange for contir	uous torque specifications	······································	305 x 305			12 x 1.0 inch)	)
11. Peak stall current, max:				120.47 A		•		
12. Rated Speed (Speed at max	continous power)			2000	•	•		
	ax at rated speed:				(7.77 h	p)		
14. Continuous torque, max, at	rated speed:		•••••	27.6 Nm	-			
15. Continuous current, Ref, at i	rated speed:		•••••	46.4 Amp	s 0 to p	peak		
16. Operating voltage, Ref (Not	for direct connection to AC line):		•••••	240 VAC	RMS			
17. Insulation class:	······································		•••••	155C (Cl	ass F)			
18. Housing temperature, max:				 125C (25	7F)			
				80 V/kRPM 0 to peak				
19. Ke, +/-10%, phase to phase at 25C +/- 5C: 20. Kt (sine), Ref, at 25C +/- 5C:				0 00 Ni /A /E 00 II- ! /A \ 0 4 I-				
20. Kt (sine), Ref, at 25C +/- 5C: 21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:					0.067 ohms			
22. Winding inductance, Ref, phase to phase:				1.57 mH				
23. Dielectric rating of motor power connections (U,V,W), to ground for 1 second:				1800 VAC RMS 50/60 Hz				
24. Audible noise, Ref, at 1 meter distance:				XX dBA				
25. Rotor inertia, +/- 10%:								
25. Rotor inertia, +/- 10%: 26. Rotor balancing quality grade:					G-0.3			
07 Full-tile te neve - Defe				0.67  Nm	(5.9 lb-	·in)		
28. Friction torque, Ref, with sha	oft and antion installed:			1.0 Nm (8		•		
29. Cogging torque, Ref:						o-in) peak t	o peak	
30. Thermal resistance, Ref, winding to ambient:				0.37 degrees C/watt				
31. Thermal time constant, Ref, winding to ambient:				83 minute				
32. Product weight, Ref:				52.6 kg (		-		
33. Shipping weight, Ref:				57.16 kg				
<ol><li>Operating ambient temperat</li></ol>	ture:			0C to 400	C (32F	to 104F)		
Notes.								
	pecifications, provided for reference only							
2. Speed, torque and current spe	ecifications are for operation with Allen l							
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	·	Dr. Scott Johnson	Date 08-26	-09	•			•

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35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	5% to 95%
37. Liquid / dust protection:	
88. Shock, max, 6 msec duration:	20 g peak
99. Vibration, max, 30 to 2000 Hz:	2.5 g peak
IO. Shaft material:	Steel, 1144
11. Paint, color:	Black
12. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	
. SIN, COS waveform output:	1024 sinusoids/rev
2. SIN, COS waveform amplitude, ± 10%:	1.0 VAC peak to peak
8. SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC:	2.2 to 2.8 VDC
i. EPVR 5V (encoder power) input voltage:	IN/A
5. EPWR 5V continuous input current,max, at 5.0 VDC:	N/A
<ul> <li>EPWR 5V continuous input current, max, at 5.0 VDC:</li> <li>EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:</li> <li>EPWR 9V (encoder power) input voltage:</li> </ul>	N/A
7. EPWR 9V (encoder power) input voltage:	7.0 to 12.0 VDC
B. EPWR 9V continuous input current, max, at 9.0 VDC:	80 mADC
EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	3.9 ADC
0. TS+, TS- thermostat operating voltage, max:	250 Volts
1. TS+, TS- thermostat continuous current, max, at 0.6 power factor:	1.6 Amps
2. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
3. DATA+, DATA- signal type, rate, asynchronous:	
4. Communication hierarchy: Encoder is slave, communication is externally initiated.	
5. Single turn absolute position value range:	0 to 32,767 (15 bit)
6. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
7. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
<ul><li>7. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.</li><li>8. Memory storage capacity, EEPROM:</li></ul>	128 bytes

## Notes:

1. "Ref" denotes untoleranced specifications, provided for reference only.



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## **Brake Specifications:**

1.	Type: S	prina-set	holding	brake.	releases	when	voltage	applied.

71 1 0 0 7	
2. Holding torque, max:	70 Nm (619 lb-in)
3. Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4. Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	2.05 ADC
5. Coil resistance, +/-10%, at 25C +/- 5C:	11.76 Ohms
6. Coil resistance, +/-10%, with motor operating at max continuous stall torque rating in a 40C ambient:	16.46 Ohms
7. Release time delay (when voltage applied), Ref:	200 msec
8. Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	
in external control circuit:	900 msec
9. Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device	
in external control circuit:	120 msec
10. Rotational backlash, Ref, with brake engaged:	25 arc minutes
11. Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:	1200 VAC RMS 50/60 Hz

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Dr. Scott Johnson Date 08-26-09

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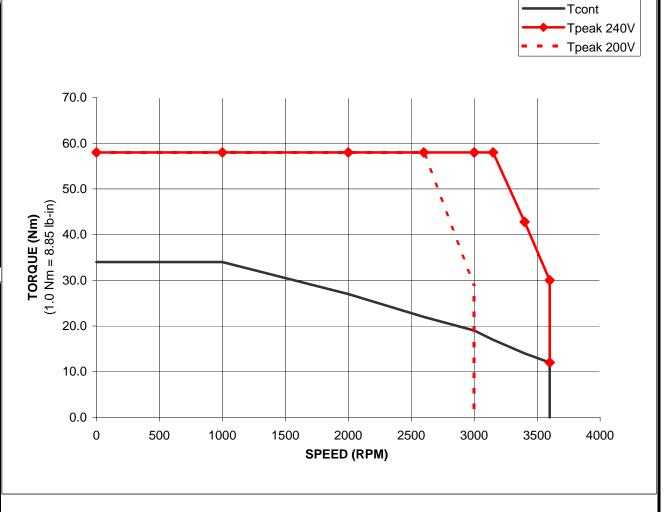
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# MPM-A2153F-Sxx4xx Performance with 2098-DSD-150, 3 Phase at 240 VAC Drive Input, 40C Motor Ambient

	TORQUE					
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V			
KEW	Nm	Nm	Nm			
0	34	58	58			
1000	34	58	58			
2000	27	58	58			
2600	22	58	58			
3000	19	58	29			
3000	19	58	0			
3150	17	58	#N/A			
3400	14	42.8	#N/A			
3600	12	30	#N/A			
3600	0	12	#N/A			
#N/A	#N/A	#N/A	#N/A			
#N/A	#N/A	#N/A	#N/A			

	TORQUE					
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V			
KEW	lb-in	lb-in	lb-in			
0	300.9	513.3	513.3			
1000	300.9	513.3	513.3			
2000	239.0	513.3	513.3			
2600	194.7	513.3	513.3			
3000	168.2	513.3	256.7			
3000	168.2	513.3	0.0			
3150	150.5	513.3	#N/A			
3400	123.9	378.8	#N/A			
3600	106.2	265.5	#N/A			
3600	0.0	106.2	#N/A			
#N/A	#N/A	#N/A	#N/A			
#N/A	#N/A	#N/A	#N/A			



## Notes:

1. Nm torque values shown are converted from tested lb-in data.

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Dr	Scott Johnson	Date	08-26-09

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