

General Specifications:	
1. Motor type: 3 phase, wye winding, permanent magnet rotor, totally enclosed, non-ventilated.	
2. Motor poles:	8
3. Operating Speed, max	4500 RPM
 Base speed (max speed at peak torque), Ref: Operating voltage at base speed: 	3100 RPM
6. Continuous stall torque, max, at max winding temperature in a 40C ambient:	5.99 Nm (53 lb-in)
7. Winding temperature, max, in a 40C ambient:	140 degrees C
8. Continuous stall current, max:	17.28 Amps 0 to peak
 8. Continuous stall current, max: 9. Heatsink size, aluminum, attached to front mounting flange for continuous torque specifications: 	305 x 305 x 12.7mm (12 x 12 x 0.5 inch)
10. Peak stall torque, max:	13.5 Nm (119 lb-in)
11. Peak stall current, max:	
12. Rated Speed (Speed at max continous power)	4000
13. Continuous output rating, max at rated speed:	1.65 kW (2.21 hp)
14. Continuous torque, max, at rated speed.	3.9 Mill (35 lb-lil)
15. Continuous current, Ref, at rated speed:	10.5 Amps 0 to peak
 15. Continuous current, Ref, at rated speed: 16. Operating voltage, Ref (Not for direct connection to AC line): 	240 VAC RMS
17. Insulation class:	155C (Class F)
18. Housing temperature, max:	125C (257F)
 Housing temperature, max: Ke, +/-10%, phase to phase at 25C +/- 5C: Ke (circa) Bet, et 25C c/ 5C: 	50 V/kRPM 0 to peak
20. Kt (Sine), Ker, at 250 +/- 50.	0.41 Nn/Anp (3.00 b-in/Anp) 0 to peak
21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:	0.591 ohms
22. Winding inductance, Ref, phase to phase:	5.09 MH
23. Dielectric rating of motor power connections (U,V,W), to ground for 1 second:	1800 VAC RMS 50/60 HZ
24. Audible noise, Ref, at 1 meter distance:	XX dBA
25. Rotor inertia, +/- 10%:	0.000983 kg-m² (0.00870 lb-in-sec²)
26. Rotor balancing quality grade:	G-6.3
27. Friction torque, Ref:	
28. Friction torque, Ref, with shaft seal option installed:	
29. Cogging torque, Ref:	
30. Thermal resistance, Ref, winding to ambient:	0.57 degrees C/watt
31. Thermal time constant, Ref, winding to ambient:	26.5 minutes
32. Product weight, Ref:	8.6 kg (19 lb)
33. Shipping weight, Rei	9.94 Kg (21.9 lb)
34. Operating ambient temperature:	0C to 40C (32F to 104F)
Notes:	
1. "Ref" denotes untoleranced specifications, provided for reference only.	
Speed, torque and current specifications are for operation with Allen Bradley drives.	
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Dr. Scott Johnson Date 0	08-26-09

35. Storage ambient temperature:		-30C to 70C (-22F to 158F)			
36. Relative humidity, non-condensing:		5% to 95%			
37 Liquid / dust protection:		IP66			
28 Shock may 6 mean duration:		20 g peak			
		2.5 g peak			
		Steel, 1144			
	surface, and connector mating surfaces are not painted.				
Feedback Specifications:					
1 SIN COS waveform output:		1024 sinusoids/rev			
3. SIN -, COS - voltage offset with respect	to ECOM ±0.3 VDC:	2.5 VDC			
4. EPWR 5V (encoder power) input voltage		4.5 to 12.0 VDC			
EPWR 5V continuous input current.max.	at 5.0 VDC:	125 mADC			
6. EPWR 5V inrush input current, max, whe	en connected to Kinetix6000 drive:	3.2 ADC			
EPWR 9V (encoder power) input voltage):	N/A			
EPWR 9V continuous input current,max,	at 9.0 VDC:	N/A			
9. EPWR 9V inrush input current, max, whe	en connected to Kinetix6000 drive:	N/A			
10. TS+, TS- thermostat operating voltage,	max:				
11. TS+, TS- thermostat continuous curren	t, max, at 0.6 power factor:	1.6 Amps			
12. TS+, TS- thermostat continuous curren	t, max, at 1.0 power factor:	2.5 Amps			
13. DATA+, DATA- signal type, rate, async	hronous:				
14. Communication hierarchy: Encoder is	slave, communication is externally initiated.				
15. Single turn absolute position value rang	Je:	0 to 32,767 (15 bit)			
16. Absolute position data: Binary, value ir	creases with CW shaft rotation viewing motor mounting face.				
17. Data (byte) format: Start bit, 8 data bits	s, parity bit, stop bit.				
18. Memory storage capacity, EEPROM:		128 bytes			
	e of encoder temperature in degrees C.				

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Brake Specifications: 1. Type: Spring-set holding brake, releases when voltage applied.	
2. Holding torque, max:	10.2 Nm (90 lb-in)
3. Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4. Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	0.64 ADC
5. Coil resistance, +/-10%, at 25C +/- 5C:	38 Ohms
6. Coil resistance, +/-10%, with motor operating at max continuous stall torque rating in a 40C ambient:	42 Ohms
7. Release time delay (when voltage applied), Ref:	110 msec
8. Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device	
in external control circuit:	160 msec
9. Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device	
in external control circuit:	25 msec
10. Rotational backlash, Ref, with brake engaged:	48 arc minutes
11. Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:	1200 VAC RMS 50/60 Hz

Notes:

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