

General Specifications:						
1. Motor type: 3 phase, wye wi	nding, permanent magnet rotor, totally e	enclosed, non-ventilated.				
2. Motor poles:				8		
Operating Speed, max				5000 RPM		
4. Base speed (max speed at p	eak torque), Ref:			3100 RPM		
Operating voltage at base sp	eed:			220 VAC RM	IS	
6. Continuous stall torque, max	, at max winding temperature in a 40C a	ambient:		6.55 Nm (58	lb-in)	
Winding temperature, max, ir	n a 40C ambient:			140 degrees	С	
8. Continuous stall current, max	c ached to front mounting flange for contir			16.18 Amps		
9. Heatsink size, aluminum, atta	ached to front mounting flange for contir	nuous torque specifications	S:	305 x 305 x 1	12.7mm (12 x 12 x 0.5 inch)	
10. Peak stall torque, max:				19.8 Nm (17	5 lb-in)	
Peak stall current, max:				64.52 Amps	0 to peak	
12. Rated Speed (Speed at max	continous power)			4000		
13. Continuous output rating, m	continous power) ax at rated speed:			1.45 kW (1.9	4 hp)	
14. Continuous torque, max, at	rated speed:			3.5 Nm (31 lb	o-in)	
15. Continuous current, Ref, at	rated speed: rated speed: rated speed: for direct connection to AC line):			8.7 Amps 0 t	o peak	
Operating voltage, Ref (Not	for direct connection to AC line):			240 VAC RM	IS	
17. Insulation class:				1000 (Class	F)	
Housing temperature, max:	e at 25C +/- 5C:			125C (257F)		
19. Ke, +/-10%, phase to phase	e at 25C +/- 5C:			54 V/kRPM (
20. Kt (Sille), Kei, at 250 +/- 50	<i>/</i> .			U.43 INIII/AIII	p (3.95 lb-in/Amp) 0 to peak	
21. Winding resistance, +/- 10%	6, phase to phase at 25C +/- 5C:			0.644 ohms		
Winding inductance, Ref, pl	nase to phase:			3.45 mH		
23. Dielectric rating of motor po	wer connections (U, v, vv), to ground for	1 second:		TOUU VAC K	MS 50/60 Hz	
Audible noise, Ref, at 1 met	ter distance:			XX dBA		
25. Rotor inertia, +/- 10%:	J			0.00089 kg-n	n² (0.00784 lb-in-sec²)	
Rotor balancing quality grad	de:			G-6.3		
27. Friction torque, Ref:				0.118 Nm (1.	04 lb-in)	
28. Friction torque, Ref, with sh	aft seal option installed:			0.38 Nm (3.4	· lb-in)	
29. Cogging torque, Ref:				0.045 Nm (0.	40 lb-in) peak to peak	
30. Thermal resistance, Ref, wi	nding to ambient:			0.60 degrees	s C/watt	
31. Thermal time constant, Ref.	, winding to ambient:			28 minutes		
32. Product weight, Ref:				8.1 kg (17.8	lb)	
33. Snipping weight, Ref:					6 lb)	
Operating ambient tempera	ture:			0C to 40C (3	2F to 104F)	
Notes:						
 "Ref" denotes untoleranced s 	pecifications, provided for reference onl	y.				
Speed, torque and current sp	ecifications are for operation with Allen					
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General Specifications, continued: 35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	IP66
37. Liquid / dust protection: 38. Shock, max, 6 msec duration:	20 g peak
39. Vibration, max, 30 to 2000 Hz:	Steel. 1144
40. Shaft material: 41. Paint, color:	Black
41. Paint, color. 42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	Dlack
42. Shart, key (ii provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	
1. SIN, COS waveform output:	1024 sinusoids/rev
 SIN, COS waveform amplitude, ± 10%: SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC: EPWR 5V (encoder power) input voltage: 	2.2 to 2.8 VDC
4. EPWR 5V (encoder power) input voltage:	4.5 to 12.0 VDC
5. EPWR 5V continuous input current,max, at 5.0 VDC:	125 mADC
6. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	3.2 ADC
7 FDMD OV / and demonstrate the second	N1/A
7. EPWR 9V (encoder power) input voltage: 8. EPWR 9V continuous input current,max, at 9.0 VDC: 9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	N/A
9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	N/A
10. TS+, TS- thermostat operating voltage, max:	250 Volts
10. TS+, TS- thermostat operating voltage, max: 11. TS+, TS- thermostat continuous current, max, at 0.6 power factor: 12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	1.6 Amps
12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	••••••
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
17. Data (byte) format. Start bit, 8 data bits, parity bit, stop bit.	128 bytes
18. Memory storage capacity, EEPROM:	120 Dytes

Notes:

1. "Ref" denotes untoleranced specifications, provided for reference only.



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Engineering Specification Electrical

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Brake Specifications:

1.	Type: Spr	ing-set holding	ı brake.	releases	when v	oltage a	applied.

2.	Holding torque, max:	4.18 Nm (37 lb-in)
3.	Voltage input, +15/-10%, may be applied either polarity:	24 VDC
4.	Current input, +/- 10%, at 24 VDC, at 25C +/- 5C:	0.50 ADC
5.	Coil resistance, +/-10%, at 25C +/- 5C:	48 Ohms
6.	Coil resistance, +/-10%, with motor operating at max continuous stall torque rating in a 40C ambient:	53 Ohms
7	Release time delay (when voltage applied). Ref:	50 msec

7. Release time delay (when voltage applied), Ref: ______50 msec 8. Engage time delay, (when voltage removed), Ref, with diode used as arc suppression device in external control circuit:

9. Engage time delay, (when voltage removed), Ref, with MOV used as arc suppression device

In external control circuit:

10. Rotational backlash, Ref, with brake engaged:

11. Dielectric rating of brake connections (MBRK+, MBRK-) to ground for 1 second:

1200 VAC RMS 50/60 Hz

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Engineering Specification Electrical MPM-A1153F-SJ74AA

Scott Johnson Date 08-26-09 Dr.

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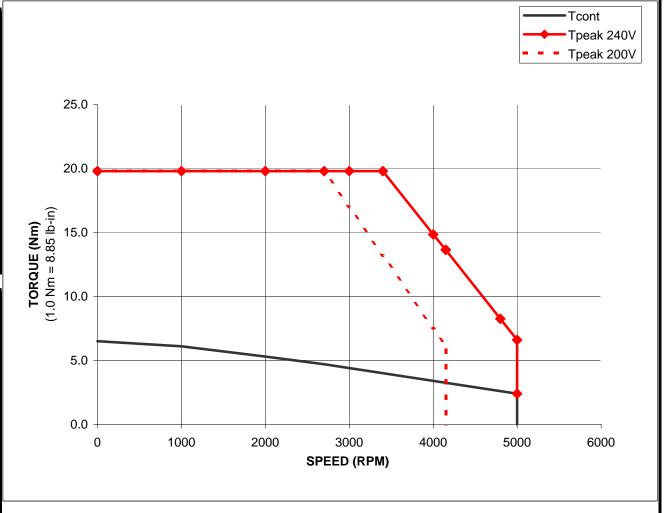
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MPM-A1153F-Sxx4xx Performance with 2094-AC16-M03, 3 Phase at 240 VAC Drive Input, 40C Motor Ambient

		TORQUE	
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V
KEW	Nm	Nm	Nm
0	6.5	19.8	19.8
1000	6.1	19.8	19.8
2000	5.3	19.8	19.8
2700	4.7	19.8	19.8
3000	4.4	19.8	17
3400	4	19.8	13.2
4000	3.4	14.85	7.5
4150	3.25	13.65	6.15
4150	3.25	13.65	0
4800	2.6	8.25	#N/A
5000	2.4	6.6	#N/A
5000	0	2.4	#N/A

	TORQUE			
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V	
IXE, IAI	lb-in	lb-in	lb-in	
0	57.5	175.2	175.2	
1000	54.0	175.2	175.2	
2000	46.9	175.2	175.2	
2700	41.6	175.2	175.2	
3000	38.9	175.2	150.5	
3400	35.4	175.2	116.8	
4000	30.1	131.4	66.4	
4150	28.8	120.8	54.4	
4150	28.8	120.8	0.0	
4800	23.0	73.0	#N/A	
5000	21.2	58.4	#N/A	
5000	0.0	21.2	#N/A	



Notes:

1. Nm torque values shown are converted from tested lb-in data.

Rockwell Automation

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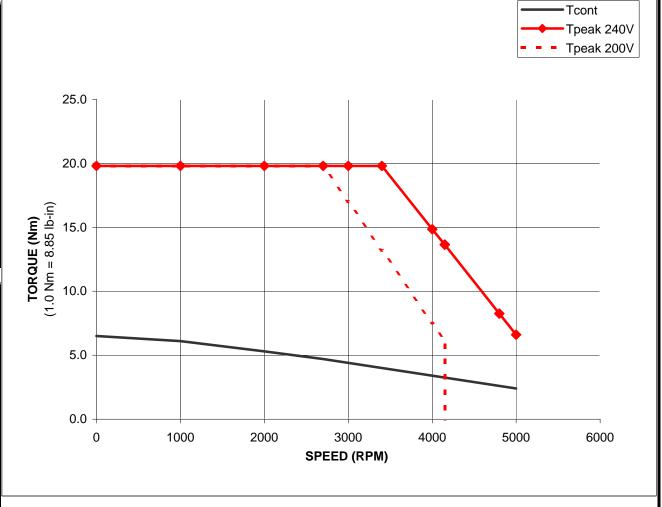
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MPM-A1153F-Sxx4xx Performance with 2094-AC32-M05, 3 Phase at 240 VAC Drive Input, 40C Motor Ambient

		TORQUE	
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V
KFIVI	Nm	Nm	Nm
0	6.5	19.8	19.8
1000	6.1	19.8	19.8
2000	5.3	19.8	19.8
2700	4.7	19.8	19.8
3000	4.4	19.8	17
3400	4	19.8	13.2
4000	3.4	14.85	7.5
4150	3.25	13.65	6.15
4150	3.25	13.65	0
4800	2.6	8.25	#N/A
5000	2.4	6.6	#N/A
5000	0	2.4	#N/A

ļ	TORQUE			
		IURQUE		
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V	
IXT IVI	lb-in	lb-in	lb-in	
0	57.5	175.2	175.2	
1000	54.0	175.2	175.2	
2000	46.9	175.2	175.2	
2700	41.6	175.2	175.2	
3000	38.9	175.2	150.5	
3400	35.4	175.2	116.8	
4000	30.1	131.4	66.4	
4150	28.8	120.8	54.4	
4150	28.8	120.8	0.0	
4800	23.0	73.0	#N/A	
5000	21.2	58.4	#N/A	
5000	0.0	21.2	#N/A	



Notes:

1. Nm torque values shown are converted from tested lb-in data.



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