

Rockwell
Automation

CONFIDENTIAL AND PROPRIETARY INFORMATION

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	Engineering	Specification	Electrical
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MPM-A1151M-MJ72AA

Dr. Scott Johnson Date 08-26-09

Sh	eet	1	of	4
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General Specifications:							
	nding, permanent magnet rotor, totally	enclosed, non-ventilated.					
2. Motor poles:			8	8			
3. Operating Speed, max			(6000 RPM			
4. Base speed (max speed at pe	eak torque), Ref:			4500 RPM			
5. Operating voltage at base spe	eed:			220 VAC RMS	6		
6. Continuous stall torque, max.	eed: , at max winding temperature in a 40C a	ambient:		2.18 Nm (19.3 lb-in)			
7. Winding temperature, max, in	a 40C ambient:			140 degrees C			
Continuous stall current, max	C						
9. Heatsink size. aluminum. atta	c: ached to front mounting flange for conti	nuous torque specifications	;;	305 x 305 x 1:	2.7mm (12 x 12 x 0.5 inch)		
10. Peak stall torque, max:		' '		6.6 Nm (58 lb	-in)		
				30.56 Amps 0			
	continous power)			5000	•		
13. Continuous output rating, ma	ax at rated speed:		(0.90 kW (1.21	hp)		
14. Continuous torque, max, at	rated speed:		······································	1.69 Nm (15 l	b-in)		
15. Continuous current, Ref, at i	rated speed:		(6.0 Amps 0 to	peak		
16. Operating voltage, Ref (Not	rated speed: rated speed: for direct connection to AC line):		2	240 VAC RMS	3		
				155C (Class F	-)		
18. Housing temperature, max:			······································	125C (257F)			
18. Housing temperature, max: 19. Ke, +/-10%, phase to phase at 25C +/- 5C:				······			
				0.04 N. /A. /0.70 H.: /A. \0.1			
21. Winding resistance, +/- 10%	b, phase to phase at 25C +/- 5C:		,	1.22 ohms			
20. Kt (sine), Ref, at 25C +/- 5C: 21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C: 22. Winding inductance, Ref, phase to phase:			Ę	5.13 mH			
23. Dielectric rating of motor power connections (U,V,W), to ground for 1 second:			,	1800 VAC RMS 50/60 Hz			
24. Audible noise, Ref, at 1 meter distance:				XX dBA			
25. Rotor inertia, +/- 10%:			(0.00065 kg-m² (0.00575 lb-in-sec²)			
26. Rotor balancing quality grad	le:		(G-6.3			
27. Friction torque, Ref:			(0.07 Nm (0.65 lb-in)			
28. Friction torque, Ref, with sha	aft seal option installed:		(0.21 Nm (1.9 lb-in)			
29. Cogging torque, Ref:			(0.028 Nm (0.25 lb-in) peak to peak			
30. Thermal resistance, Ref, winding to ambient:				0.71 degrees C/watt			
31. Thermal time constant, Ref, winding to ambient:				16 minutes			
32. Product weight, Ref:				3.45 kg (7.6 lb			
33. Shipping weight, Ref:				4.65 kg (10.24			
34. Operating ambient temperature:				0C to 40C (32	F to 104F)		
Notes:							
	pecifications, provided for reference on	=					
Speed, torque and current speed	ecifications are for operation with Allen	<u> </u>					
Declare	CONFIDENTIAL AND PROPRIETARY INFORMATION	Engineering Specification	on Electrical	She	et 2 of	4	
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Automation	OF ROCKWELL AUTOMATION, INC. AND MAY NOT BE USED, COPIED OR DISCLOSED TO OTHERS, EXCEPT WITH THE AUTHORIZED WRITTEN PERMISSION OF ROCKWELL AUTOMATION, INC.			- A	10000073869	01	
	ambook of RoomElection and the fire	Dr. Scott Johnson	Date 08-26-09			01	

General Specifications, continued:	000 (- 700 (005 (- 4505)
35. Storage ambient temperature:	-30C to 70C (-22F to 158F)
36. Relative humidity, non-condensing:	5% to 95%
37. Liquid / dust protection:	IP66
38. Shock, max, 6 msec duration:	20 g peak
39. Vibration, max, 30 to 2000 Hz:	2.5 g peak
40. Orial Malerial.	
41. Paint, color:	Black
42. Shaft, key (if provided), front mounting surface, and connector mating surfaces are not painted.	
Feedback Specifications:	4004 :
1. SIN, COS waveform output:	1024 sinusoids/rev
2. SIN, COS waveform amplitude, ± 10%:	1.0 VAC peak to peak
3. SIN -, COS - voltage offset with respect to ECOM ±0.3 VDC:	2.5 VDC
4. EPWR 5V (encoder power) input voltage:	4.5 to 12.0 VDC
5. EPWR 5V continuous input current,max, at 5.0 VDC:	125 mADC
6. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	3.2 ADC
7. EPWR 9V (encoder power) input voltage:	N/A
8. EPWR 9V continuous input current,max, at 9.0 VDC:	N/A
9. EPWR 9V inrush input current, max, when connected to Kinetix6000 drive:	N/A
10. TS+, TS- thermostat operating voltage, max:	250 Volts
11. TS+, TS- thermostat continuous current, max, at 0.6 power factor:	1.6 Amps
12. TS+, TS- thermostat continuous current, max, at 1.0 power factor:	2.5 Amps
13. DATA+, DATA- signal type, rate, asynchronous:	DC 40F 0600 haud
14. Communication hierarchy: Encoder is slave, communication is externally initiated.	
15. Single turn absolute position value range:	0 to 32,767 (15 bit)
16. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
17. Data (byte) format: Start bit, 8 data bits, parity bit, stop bit.	
18. Memory storage capacity, EEPROM:	128 bytes
 Encoder temperature data: Binary value of encoder temperature in degrees C. 	

Notes:

1. "Ref" denotes untoleranced specifications, provided for reference only.



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Engineering Specification Electrical

Dr.

 MPM-A1151M-MJ72AA

 Scott Johnson
 Date
 08-26-09

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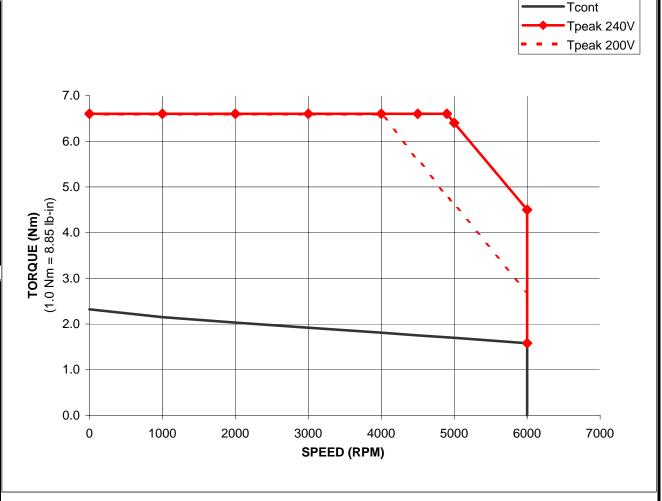
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MPM-A1151M-Mxx2xx Performance with 2094-AC09-M02, 3 Phase at 240 VAC Drive Input, 40C Motor Ambient

	TORQUE			
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V	
KPIVI	Nm	Nm	Nm	
0	2.32	6.6	6.6	
1000	2.15	6.6	6.6	
2000	2.03	6.6	6.6	
3000	1.92	6.6	6.6	
4000	1.81	6.6	6.6	
4500	1.75	6.6	5.6	
4900	1.71	6.6	4.8	
5000	1.7	6.4	4.6	
6000	1.58	4.5	2.7	
6000	0	1.58	#N/A	
#N/A	#N/A	#N/A	#N/A	
#N/A	#N/A	#N/A	#N/A	

	TORQUE			
SPEED RPM	Tcont	Tpeak 240V	Tpeak 200V	
KEW	lb-in	lb-in	lb-in	
0	20.5	58.4	58.4	
1000	19.0	58.4	58.4	
2000	18.0	58.4	58.4	
3000	17.0	58.4	58.4	
4000	16.0	58.4	58.4	
4500	15.5	58.4	49.6	
4900	15.1	58.4	42.5	
5000	15.0	56.6	40.7	
6000	14.0	39.8	23.9	
6000	0.0	14.0	#N/A	
#N/A	#N/A	#N/A	#N/A	
#N/A	#N/A	#N/A	#N/A	



Notes:

1. Nm torque values shown are converted from tested lb-in data.

Dr.

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